Selected Topics Communications and Mobile Computing (Smart Health)

TU Graz University of Notre Dame





Computer Science and Engineering - University of Notre Dame

Sensors & Sensing

 A sensor is a converter that measures a physical quantity and converts it into a signal which can be read by an instrument



Visual Sensor



Ultrasound Sensor



Infrared Sensor

Basic Terms

- **Transducer:** a device which converts one form of energy to another
- Sensor: a transducer that converts a physical phenomenon into an electric signal
 - Interface between the physical world and the computing world
- Actuator: a transducer that converts an electric signal to a physical phenomenon



Sensor/Actuator System



Sensor-to-Signal Interface

- Action of environment on a sensor causes it to generate an electrical signal directly
 - voltage source (V), current (I), or charge (Q) source
- Action of environment on sensor changes an electrical parameter that we can measure
 - Resistance changes: V = I * R (R = resistance)
 - Capacitance changes: C = $\epsilon * A / d$ (A = area, d = distance, $\epsilon = permittivity$)
 - Inductance changes: $V \sim dI/dt$, $I \sim \int V dt$

Signal Conditioning

- Filter for expected frequency regime
- Subtract DC offset ("zeroing")
- Amplify or attenuate signal ("scaling")
- Linearize relationship between measured and observed electrical parameter

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Analog-to-Digital Converter (ADC)

- Many different principles
- All involve trade-offs of speed (conversion time), resolution (number of bits), and cost
- "Flash converter" is the fastest, has the lowest resolution, and the highest cost
- Successive approximation ADC: binary search through all possible quantization levels

Example

$$Q = \frac{E_{FSR}}{2^M} = \frac{E_{FSR}}{N}$$

- Q = resolution in volts per step
- M = resolution in bits
- N = Number of intervals (steps)
- E_{FSR} = Full scale voltage range
- Voltage range 0 10V; M = 12 bits
- N = 4096 intervals (steps)
- Q = 2.44 mV/code



Sensor Types

Criterion	Classes	Example
Power supply	Modulating	Thermistor*
	Generating	Thermocouple**
Output signal	Analog	Potentiometer
	Digital	Position encoder
Operating mode	Deflection	Deflection accelerometer
	Null	Servo-accelerometer

**Thermistor*: a resistor whose resistance changes with temperature.

** Thermocouple: a temperature-sensing element which converts thermal energy directly into electrical energy

Sensor Types: Power Supply

- Modulating
 - Also known as Active Sensors
 - They need auxiliary power to perform functionality
- Self-Generating
 - Also known as Passive Sensors
 - They derive the power from the input

Sensor Types: Operating Mode

- Deflection
 - The measured quantity produces a physical effect
 - Generates an apposing effect which can be measured
 - Faster
- Null
 - Applies the counter force
 - To balance the deflection from the null point (balance condition)
 - Can be more accurate but slow

Sensor Types: Physical Property

- Temperature
- Pressure
- Humidity
- Light
- Microphone (sound)
- Motion detector
- Chemical detector
- Image Sensor
- Flow and level sensor

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Sensor Types: HW & SW

- Hardware-based sensors
 - Physical components built into a device
 - They derive their data by directly measuring specific environmental properties
- Software-based sensors
 - Not physical devices, although they mimic hardware-based sensors
 - They derive their data from one or more hardware-based sensors

Sensor Types: Function Type

- Motion sensors
 - Measure acceleration forces and rotational forces along three axes, e.g., accelerometer, gyroscope, etc.
- Position sensors
 - Measure the physical position of a device, e.g., GPS, proximity sensor, etc.
- Environmental sensors
 - Measure various environmental parameters, e.g., light sensor, thermometer, etc.

Sensor List

Sensor	Function Type	Software-based or Hardware-based
Accelerometer	Motion Sensor	Hardware-based
Gyroscope	Motion Sensor	Hardware-based
Gravity	Motion Sensor	Software-based
Rotation Vector	Motion Sensor	Software-based
Magnetic Field	Position Sensor	Hardware-based
Proximity	Position Sensor	Hardware-based
GPS	Position Sensor	Hardware-based
Orientation	Position Sensor	Software-based
Light	Environmental Sensor	Hardware-based
Thermometer	Environmental Sensor	Hardware-based
Barometer	Environmental Sensor	Hardware-based
Humidity	Environmental Sensor	Hardware-based

Smartphone and Wearable Sensing

- Light
- Proximity
- Cameras (multiple)
- Microphones (multiple)
- Touch
- Position
 - GPS, Wi-Fi, cell, NFC, Bluetooth
- Accelerometer
- Gyroscope
- Magnetometer
- Pressure
- Temperature
- Humidity
- Fingerprint sensor



- Accelerometer
- Gyroscope
- Microphone
- Position
- Infrared thermopile
- Photoplethysmography (PPG)
- Electrodermal activity (EDA)
- Electrocardiogram (ECG)



Sensor: GPS

- Need connection to 3 satellites for 2D positioning, 4 satellites for 3D positioning (theoretically)
- More visible satellites increase precision
- Based on concept of trilateration



Sensor: Motion and Orientation

- Most of the sensors use the same **coordinate system**
- When a device's screen is facing the user
 - The X axis is horizontal and points to the right
 - The Y axis is vertical and points up
 - The Z axis pints toward outside of the screen face



Sensor: Accelerometer

- Measure proper acceleration (acceleration it experiences relative to freefall)
- Units: g

Example	G Force
Standing on earth at sea level	lg
Bugatti Veyron from 0 to 100 km/h (2.4s)	1.55g
Space Shuttle, maximum during launch and reentry	3g
Formula 1 car, peak lateral in turns	5-6g
Death or serious injury	50g
Shock capability of mechanical Omega watches	5000g

Sensor: Accelerometer

- Acceleration is measured on 3 axes
- Note that the force of gravity is always included in the measured acceleration
 - When the device is sitting on the table stationary, the accelerometer reads a magnitude of 1g
 - When the device is in free fall, the accelerometer reads a magnitude of 0g
- To measure the real acceleration of the device, the contribution of the force of gravity must be removed from the reading, for example, by calibration

Sensor: Accelerometer

- When the device is lying flat
 - gives +1g (gravitational force) reading on Z axis
- Stationary device, after 45 degree rotation
 - Same magnitude, but rotated



Accelerometer: Inner Working (1 of 2)



It consists of beams and a capacitive sensor with some anchor points

Accelerometer: Inner Working (2 of 2)



On applying the acceleration, the beams deflect and cause the change in capacitance.

Accelerometer



Smartphones: MEMS Sensors

- Micro Electro-Mechanical Systems
- Term coined in 1989
- Describes creation of mechanical elements at a scale more usually reserved for microelectronics
- MEMS use cavities, channels, cantilevers, membranes, etc. to imitate traditional mechanical systems
- Small enough to be integrated with the electronics



MEMS Accelerometer





- Have a proof mass between springs and a series of 'plates'
- Measure deflection via capacitance changes
 - 1-D only

Sensor: Gravity

- Gravity sensor is not a separate hardware
- It is a virtual sensor based on the accelerometer
- It is the result when real acceleration component is removed from the reading

Sensor: Gyroscope

- Measures the rate of rotation (angular speed) around an axis
- Speed is expressed in rad/s on 3 axis
- When the device is not rotating, the sensor values will be zeros
- It gives us 3 values
 - Pitch value (rotation around X axis)
 - Roll value (rotation around Y axis)
 - Yaw value (rotation around Z axis)



- Unfortunately, gyroscope is error prone over time.
- As time goes, gyroscope introduces drift in result
- By sensor fusion (combining accelerometer and gyroscope), results can be corrected and path of movement of device can be obtained correctly

Gyroscope



- 1. Normally, a drive arm vibrates in a certain direction.
- 2. Direction of rotation
- 3. When the gyro is rotated, the Coriolis force acts on the drive arms, producing vertical vibration.
- 4. The stationary part bends due to vertical drive arm vibration, producing a sensing motion in the sensing arms.
- 5. The motion of a pair of sensing arms produces a potential difference from which angular velocity is sensed. The angular velocity is converted to, and output as, an electrical signal.

MEMS Gyroscope







- Based on measuring Coriolis force as experienced by a moving object in a rotating frame of reference
- Many implementations, but the "tuning fork" method is most common

Accelerometer vs. Gyroscope

- Accelerometer
 - Senses linear movement: not good for rotations, good for tilt detection
 - Does not know difference between gravity and linear movement
- Gyroscope
 - Measures all types of rotations
 - Not movement
- A+G = both rotation and movement tracking possible

Sensor: Magnetic Field

- Measures direction and strength of earth's magnetic field
- Strength is expressed in tesla (T)

Example	Field strength
Earth's magnetic field on the equator (0° latitude)	31µT (0.00031T)
Typical fridge magnet	5mT (0.005T)
Strong neodymium magnet	1.25T
MRI system	I.5T – 3T

Compass

• Magnetic field sensor (magnetometer)



MEMS Compass

- Most use Lorentz Force
- A current-carrying wire in a magnetic field experiences a perpendicular force





Sensor: Proximity

- A proximity sensor can detect the presence of nearby objects without physical contact
- It often emits an electromagnetic field (e.g., infrared) and looks for changes in the field or return signal
- It is usually used by mobile device to determine how far a person's head is from the face of a handset
 - E.g., a user is making a phone call



- The measured results could be different based on different devices
 - Most proximity sensors return the absolute distance in centimeters (cm)
 - Some return only a flag that represents near or far
 - Some return either 0.0 or the maximum value only
Sensor: Light

- It gives a reading of the light level detected by the light sensor of the device
- Located at front of mobile device near to front facing camera
- The units are in SI lux units
- The device uses the data to adjust the display's brightness automatically
 - When ambient light is plentiful, the screen's brightness is pumped up and when it is dark, the display is dimmed down
 - High-end Samsung galaxy phones use an advanced light sensor that can measure white, red, green, and blue light independently to fine tune image representation



Sensor: Thermometer

- Ambient temperature outside of the device
- In fact, there's a thermometer in almost every mobile device and some handsets might have more than one of them; however, they are used to monitor the temperature inside the device and its battery to detect overheating
- A temperature sensor detects a change in a physical parameter such as resistance or output voltage that corresponds to a temperature change
- Contact (direct physical contact) vs. non-contact (radiant energy of a heat source)



Sensor: Pressure

- Transduces pressure into electrical quantity
- Pressure exerts force which can be converted to electrical voltage using various methods
- Strain Gauges
 - Based on the variation of resistance of a conductor or semiconductor when applied to mechanical stress

• Capacitive diaphragms

- Diaphragm acts as one plate of capacitor
- The stress changes the space between capacitor plates

• Piezo-resistive

- Micro-machined silicon diaphragms
- Piezo-resistive strain gauges diffused into it
- Very sensitive to pressure







Piezoelectric Sensors

- Device that measures changes in pressure, strain, force, etc. by converting them to an electrical charge
- Typically crystals or ceramics



Sensor: Sound

- A **microphone** is an acoustic to electric transducer that converts sound into an electrical signal
- Microphones capture sound waves with a thin, flexible diaphragm; the vibrations of this element are then converted by various methods into an electrical signal that is an analog of the original sound.
- Most microphones in use today use electromagnetic generation (dynamic microphones), capacitance change (condenser microphones) or piezo-electric generation to produce the signal from mechanical vibration.

Condenser (or Capacitor) Microphones

- In a condenser microphone, the diaphragm acts as one plate of a capacitor, and the vibrations produce changes in the distance between the plates.
- Since the plates are biased with a fixed charge (Q), the voltage maintained across the capacitor plates changes with the vibrations in the air.



Dynamic Microphones

- In a dynamic microphone, a small movable induction coil, positioned in the magnetic field of a permanent magnet, is attached to the diaphragm.
- When sound enters through the windscreen of the microphone, the sound wave vibrations move the diaphragm.
- When the diaphragm vibrates, the coil moves in the magnetic field, producing a varying current in the coil through **electromagnetic induction**.



Microphones in Smartphones

- Almost all new handsets use MEMS microphones (often plural!)
- Two conducting membranes, one on top of the other, acting as a capacitor
- Vibrations cause the capacitance to change



Sensor: Cameras

- These vary, but more and more make use of MEMS for (auto)focus
- The underlying light sensor is no different from 'normal' cameras
- However the small, cheap lenses inevitably suffer from distortion



Distortion Correction

- Calibrate lens -> Remove distortion
- But this is a costly process



Camera Sensor

- With such small apertures, longer exposures are needed to get good output
- Hence phone cameras suffer from extensive noise in
 low light levels
 - Photon shot noise



Continuous Sensing

- Most of the smartphone OSes assume you don't want to register for 24/7 sensing events
- If you do, watch out that the OS doesn't require some extra action on your part
 - e.g., some versions of Android put the CPU into a low power state after a certain time of screen inactivity. The lowest power states preclude polling the sensor data...!
- You might have to hold a wake lock on the CPU if you want to do this (which means the battery will deplete faster!)

Nominal Rates

- The sensor hardware samples at a constant ('nominal') rate but timestamping is error-prone
- Hence most smartphone APIs shy away from numerical rates. Android uses:

```
case SENSOR_DELAY_FASTEST:
    delay = 0;
    break;
case SENSOR_DELAY_GAME:
    delay = 20000;
    break;
case SENSOR_DELAY_UI:
    delay = 66667;
    break;
case SENSOR_DELAY_NORMAL:
    delay = 200000;
```

Sampling

- Smartphone OSes are not real-time. Most sensors regularly update a register with values. The updates produce interrupts and eventually the OS gets around to collecting the value.
- If the OS is busy already, a new value could come in before we've read the last!
- Dropped readings...
- More recent sensors use a ring buffer so we don't drop any, but...
- The timestamps are currently of the time the datum was collected and not the instant it was created...

Nominal Rate Example (Nexus S)



Sensor Filtering

- Warning: sometimes getting a higher sampling rate is pointless
- More and more sensors now have built-in low-pass filtering, which limits the max. frequency present. So high sampling rates might just result in oversampling!
- Normally not an issue (in fact a good thing) but wastes power and performance

Process Interference

- Sampling consistency can also be affected by high priority resource-intensive processes. In Android 2.3, the garbage collector ran with a higher priority than sensing...
- And other processes may request a higher rate for the same sensor at the same time! The logical thing is to run at the highest requested rate, but this might mean your app sees significant jumps in the rate of events.

Derived Sensors

- Initially the sensor access was raw, but now we have derived sensor types that fuse raw data to estimate other quantities. E.g., in Android:
 - TYPE_GRAVITY Estimates the gravity vector by low pass filtering the accelerometers
 - TYPE_LINEAR_ACCELERATION Estimates the acceleration having subtracted gravity
 - TYPE_ROTATION_VECTOR Estimates the full rotational pose of the sensor in a world frame
- Specific implementation details vary (e.g. software/hardware, gyroscope for rotation or not)
- Can ignore and fuse ourselves of course...

Inertial Tracking

- It is very tempting to fuse the sensors together to track the phone's trajectory → Inertial Measurement Unit
- Such tracking is relative; errors accrue over time (drift)

Example: Linear Acceleration

 If the pose of the device is constant, double integrating the accelerometers after removing gravity should give displacement

- Error grows quadratically over time
- End result is a fast (and unlimited) accrual of error

Sensor Alignment

- It can be dangerous to assume the three sensors in a 3-D sensor are:
 - Perfectly orthogonal
 - Perfectly parallel to those of other sensors



Electrocardiogram (Heart Activity)



Electrocardiogram (Heart Activity)



Electrocardiogram (Heart Activity)





The P wave is associated with the contractions of the atria (the two chambers in the heart that receive blood from outside)

The QRS is a series of waves associated with ventricular contractions (the ventricles are the two major pumping chambers in the heart)

The T and U waves follow the ventricular contractions

https://www.youtube.com/watch?v=gWakpOAxWAU

ECG Applications

- Diagnostics
- Functional analysis
- Implants (pace maker)
- Biofeedback (neartrate variability, HRV)
- Peak performance training, monitoring

Electromyogram (Muscle Movement)





EMG surface (glue-)electrodes

EMG - signal (up to 3mV, 1kHz)

Electromyogram (Muscle Movement)



Recording locations for facial EMG

EMG Applications

- Rehabilitation
- Functional analysis
- Active prosthetics
- Biomechanics, sports medicine

Electrooculogram (Eye Movement)

Augenbewegung Links



EOG Applications

- Diagnostics
- Functional analysis
- Human-computer interfaces





EEG electrode cap

MMMMMmmmmmmMMMMMMMMmmmm 13-30 Hz β Beta MMMM 8-12 Hz α Alpha MMMMMM 4−7 Hz ϑ Theta 0,5–3 Hz δ Delta 1 5

- Delta (up to 4Hz)
 - Front in adults, back in children
 - Sleep, babies, during some continuous attention tasks
 - (subcortical lesions, diffuse lesions, ...)
- Theta (4-8Hz)
 - Locations not related to task at hand
 - Young children, drowsiness or arousal, idling
 - (focal subcortical lesions, deep midline disorders, ...)
- Alpha (8-13Hz)
 - Posterior regions, both sides
 - Relaxed, reflecting, closing eyes, inhibition control
 - (coma)
- Beta (13-30Hz)
 - Both sides, symmetrical distribution
 - Alert/working; active, busy or anxious thinking, active concentration
 - (benzodiazepines)



EEG artifacts: Eye blinks, muscle tension

EEG Applications

- Diagnostics (epilepsy, oncology, ..)
- Cognitive sciences
- Sleep analysis
- Human computer interfaces (BCIs)
- Pharmacology
- Intensive care, monitoring

Other Biosignals





Blood volume

Infrared plethysmography
Other Biosignals

- Pulse oximeter
- Non-invasive technology used to measure the heart rate (HR) and blood oxygen saturation (SpO₂)
- Project infrared and near-infrared light through blood vessels near the skin
- Detect the amount of light absorbed by hemoglobin in the blood at two different wavelengths to help determine level of oxygen
- Blood vessels contract and expand with the patient's pulse which affects the pattern of light absorbed over time
- Computation of HR and SpO₂ from the light transmission waveforms can be performed using standard DSP algorithms



Other Biosignals

Breathing sensors (thermal/optical/mechanoresistive)



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Other Biosignals



Galvanic skin response (GSR) Electrodermal activity (EDA) Skin conductance level (SCL)



Peripheral body temperature

Biomedical Measurements

Biomedical measurements	Voltage range (V)	Number of users = <i>K</i> (sensors)	Bandwidth (Hz)	Sample rate (samples/s) = (Hz)	Resolution [b/sample]	Information rate [b/s]
ECG	0.5–4 m	5–9	0.01–250	1250	12	15,000
Heart sound	Extremely small	2–4	5–2000	10,000	12	120,000
Heart rate	0.5–4 m	2	0.4–5	25	24	600
EEG	2–200 μ	20	0.5–70	350	12	4200
EMG	0.1–5 m	2+	0–10,000	50,000	12	600,000
Respiratory rate	Small	1	0.1–10	50	16	800
Temperature of body	0–100 m	1+	0–1	5	16	80

Bandwidth = $f_{max} - f_{min}$ Sample rate = 5_f_{max} Information rate = R_b = Resolution_Sample rate

S. Arnon, et al., "A Comparative Study of Wireless Communication Network Configurations for Medical Applications," IEEE Wireless Communications, pp. 56-61, February 2003

From Smart Devices to Crowdsensing



Technical Enabler 1: Powerful Embedded Sensors in Smartphones



Technical Enabler 2: Open and Programmable









Technical Enabler 3: App Store









Technical Enabler 4: Mobile Computing Cloud



MCS Paradigm



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Sensing Paradigms

- Participatory Sensing
 - Users actively engage in the "sensing process"
 - Human intelligence can be leveraged for complex tasks
 - More costs or incentives are needed to keep humans involved
 - Privacy issues
- Opportunistic Sensing
 - Fully automated and no user involvement
 - Less burden and costs on the user
 - Detect the phone context
 - Humans are underutilized
 - Privacy and energy issues

MCS: Unique Characteristics

- Multi-modal sensing capabilities
- Deployed in the field (remote sensing/management)
- Device diversity; resource limitations
- Dynamic conditions
- Privacy concerns
- Energy consumption
- Amounts of data
- Effort/cost vs. incentives; compliance
- False data
- Labeling/annotations
- Localized/aggregate analytics

Sensing

- Programmability:
 - Lack of low level sensor control
 - Different vendors offer different APIs
- Continuous sensing:
 - Need to support multitasking and background processing
 - Limited battery power on mobile phones
- Phone context:
 - Phones are used on the go and in different contexts (e.g., in vs. out of pocket)
 - Anticipating all possible different phone usage scenarios is very difficult

Learning

- Human behavior and context modeling
 - Supervised learning (small scale)
 - Semi-supervised/Unsupervised (medium to large scale)
 - Learn activities (e.g., brushing teeth, driving, running)
 - Learn places (e.g., work, home, coffee shop)



Urban Sensing Apps

- Noise mapping
- Emotion mapping
- Congestion charging





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NetHealth Study

• Smartphone Sensor Data

Device	Data Type	Sampling Period (Min.)
iPhone	Location (Latitude, Longitude, Accuracy)	2.75
Fitbit	Step Counts, activity levels (sedentary, light, fair, high), Calorie burn, Heart rate	1

- Subjects
 - 467 iPhone users (on-campus freshmen)
 - Avg. age ~17y 11m (SD = 11m)
 - Fall 2015 Fall 2016





Sensing Example: Location Hotspots



Subjects' locations during daytime hours

Subjects' locations during nighttime hours

Motivation

- Assess a user's quality of life through analysis of
 - Place visits and mobility patterns, social interactions, and levels of physical activity
- Researchers and healthcare providers can monitor patient behavior remotely
 - E.g., assess the effectiveness of stroke therapy
- Deliver place-specific mobile health interventions
 - E.g., encourage individuals to work out when near gyms or parks
- Deliver **customized surveys** to an individual's phone
 - E.g., social interaction surveys, or mood surveys

Continuous Health Monitoring

- Opportunities of continuous monitoring:
 - Identify mobility patterns
 - Time spent indoors/outdoors; type of transportation; locations visited
 - Recognize social interactions
 - Electronic communications (email, phone, SMS, chat)
 - In-person meetings (individual/group, type of meeting, venue)
 - Identify activities
 - Healthy/unhealthy habits, routine household activities, physical activities
 - Other health-related information and events
 - Sleep times/quality, stress, moods, falls and other injuries

Continuous Health Monitoring



The CIMON Monitoring Toolkit

- Configurable Integrated MONitoring Toolkit
- Powerful smartphone monitoring system for Androidbased devices:
 - Monitor sensor activities (e.g., GPS, accelerometer, gyroscope, microphone, barometer, magnetometer, etc.)
 - Monitor user activities (e.g., communications, apps, music, browsing, etc.)
 - Monitor system activities (e.g., resource usage, network connections and traffic, etc.)
- Configurable to meet sensing needs of specific (health) situation

Screenshots of Configuration Screens

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CIMON Monitor	_	CIMON Monitor		CIMON Monitor			CIMON Monitor		
System Sensors	User Activity	System	((c) Sensors User Activity	System	Sensors	User Activity	System	Sensors	User Activity
Geo-location	inactive	CPU utilization	Frequency: 1.000 Hz	Geo-location	Frequen	icy: 0.999 Hz			
network passive gps	Power: 3.0mA	BogoMIPS: 13.53	Power: 0.0mA	network passive gps		Power: 3.0mA	Period 1 s		Frequency 1.000 Hz
Accelerometer	inactive	Total	100 %	latitude	39.48	3°			
MPL accel	Power: 0.5mA		17%		-87 32	•			
Magnetometer	inactive	0301			01.02		0.01		100
MPL magnetic field	Power: 0.5mA	Nice	0 %	Accuracy	0 r	m	Duration		
Gyroscope	inactive	System	10%	Accelerometer	Frequen	icy: 0.970 Hz 👝	Manual		
MPL Gyro	Power: 0.5mA		10.0	MPL accel	1	Power: 0.5mA		120	min 🔻
Linear Acceleration	inactive	ldle	68 %	Magnetometer	Frequen	icy: 1.000 Hz			
MPL linear accel	Power: 0.5mA	IOWait	3%	MPL magnetic field		Power: 0.5mA	Include i	metadata in report	
Orientation	inactive			Gyroscope		inactive			
MPL Orientation (android deprecated format)	Power: 9.7mA	IRQ	0 %	MPL Gyro		Power: 0.5mA			
Proximity sensor	inactive	Soft IRQ	0 %	Linear Acceleration		inactive	Email		Google Drive
GP2A Proximity Sensor	Power: 0.75mA			MPL linear accel		Power: 0.5mA	Proximity sense		
Pressure	inactive (j)	Context switches	1811	Orientation	Frequen	icy: 0.972 Hz	G Box		Dropbox
BMP180 Pressure Sensor	Power: 0.05mA	Battery	inactive	MPL Orientation (android de	eprecated format)	Power: 9.7mA			
Minimum interval: 15 ms	^	Li-ion	Power: 0.0mA	Azimuth	0.81 ra	d	P Duri		Ormani
Maximum range: 1100.0 hPa Besolution: 0.01 hPa		Network traffic	Frequency: 1.000 Hz 💼				B	bra	Cancel
Light concer	inactive -	Active network: WIFI	Power: 0.0mA	Pitch	-1.12 ra	nd	Atmospher		0 hPa
GP2A Light Sensor	Power: 0.75mA	Obile Rx	82117368 bytes	Roll	2. <u>05</u> ra	d Contraction			
		Mobile Tx	28946248 bytes	Proximity sensor	Frequen	icy: 1.000 Hz	Light sensor GP2A Light Sensor		Power: 0.75mA
		Total Rx	881502592 bytes	GP2A Proximity Sensor	P	ower: 0.75mA	Light level		0 lux

CIMON Framework



Smartphone Sensors

Sensor Name	Туре	Status	Tested	Period
Memory	System	Integrated	Yes	1s
CPU load	System	Integrated	Yes	1s
CPU utilization	System	Integrated	Yes	1s
Battery	System	Integrated	Yes	1s
Network traffic	System	Integrated	Yes	1s
Connectivity status	System	Integrated	Yes	1s
Instruction count	System	Integrated	Yes	1s
SDCard accesses	System	Integrated	Yes	1s
Geo-location	Sensors	Integrated	Yes	10s
Accelerometer	Sensors	Integrated	Yes	100ms
Magnetometer	Sensors	Integrated	Yes	100ms
Gyroscope	Sensors	Integrated	Yes	100ms
Linear Acceleration	Sensors	Integrated	Yes	100ms
Orientation	Sensors	Integrated	No	100ms
Proximity sensor	Sensors	Integrated	No	1s
Pressure	Sensors	Integrated	No	1s
Light sensor	Sensors	Integrated	No	1s
Humidity	Sensors	Not Integrated	Failed	1s
Temperature	Sensors	Not Integrated	Failed	1s
Screen state	User Activity	Integrated	No	3min

Smartphone Sensors

Sensor Name	Туре	Status	Tested	Period
Phone Activity	User Activity	Integrated	No	1s
SMS activity	User Activity	Integrated	No	1s
MMS activity	User Activity	Integrated	No	1s
Bluetooth activity	User Activity	Integrated	Yes	3min
Wifi activity	User Activity	Integrated	Yes	3min
Application	N/A	Implemented, Not Integrated	No	1min
Audio	N/A	Implemented, Not Integrated	No	10min
Browsing History	N/A	Implemented, Not Integrated	No	1min
Call State	N/A	Implemented, Not Integrated	No	1min
Cell Location	N/A	Implemented, Not Integrated	No	10s
Media Store Image	N/A	Implemented, Not Integrated	No	5min
Media Store Video	N/A	Not Implemented	No	5min
MMS Information	N/A	Not Implemented	No	1s
Phone Call Information	N/A	Not Implemented	No	1s
Phone Identity	N/A	Not Implemented	No	10min
SMS Information	N/A	Implemented, Not Integrated	Yes	1s

Examples of Sensing Capabilities

Sensor Type	Sensing Examples
GPS & Triangulation	Locations, routes, indoor/outdoor time
Accelerometer	Mode of transportation, activities, step counters
Gyroscope	Type of activities, unusual events (falls)
Wi-Fi Proximity	Locations, routes
Bluetooth Proximity	Proximity to friends, family, coworkers, etc.
Magnetometer	Type of activities
NFC/RFID	Locations (supermarket, library, etc.)
Barometer	Locations (floor of building)
Applications	Preferences, moods, interests/hobbies
Phone, EMail, SMS	Communication patterns, moods
Media (Music, Pictures,)	Preferences, interests, moods

Technical Challenge: Battery Life



Current research focus: *collect maximum amount of data at highest quality possible, while making sure that device will last 14-16 hours* (typical time between recharging)

CIMON Sensing App: Labeling Interface

- Allows subjects to track common types of activities
- Used for development of activity detection algorithms
- In addition to pre-defined activities, subjects can add custom activities



That's It For Today

