

Shared Access Networks

Outline

- Bus (Ethernet 802.2/3)
- Token ring
- Wireless (802.11)

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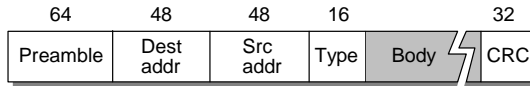
Ethernet Overview

- The most successful Local Area Networks
- Bandwidth: 10Mbps, 100Mbps (Fast), 1Gbps
- Avoid Simultaneous on a Shared Line: CSMA/CD
 - multiple access
 - carrier sense:
 - listen before transmitting.
 - distinguish an idle and busy link.
 - collision detection
 - listen while transmitting.
 - Collision: What you hear is different from what you listen

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Ethernet Frame

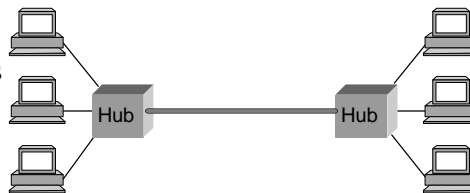
- Frame Format
- Addresses
 - unique, 48-bit unicast address assigned to each adapter
 - example: **8:0:e4:b1:2**
 - Every body hears the frame (shared media). But the one with matching destination address picks up.
 - broadcast: all 1s
 - multicast: first bit is **1**. The host can configure its adaptor to accept some multicast addresses
- Preamble (a seq. alternating 0s and 1s) indicates the start of a frame
- Type: high-level protocols



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Ethernet Repeater

- Repeaters
 - Amplifier forwarding signals
 - Segments separated by repeaters are in the same collision domain
- Max Length: 2500m
 - A coaxial copper cable of up to 500m
 - segments with 4 repeaters
 - max round-trip delay: 51.2us



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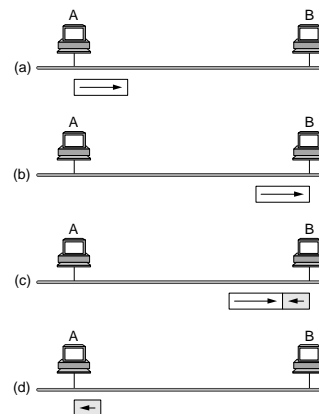
Transmit Algorithm

- If line is idle...
 - send immediately
 - upper bound message size of 1500 bytes
 - Limited occupancy on the line.
 - must wait 9.6 μ s between back-to-back frames
 - To allow other hosts to send.
- If line is busy...
 - wait until idle and transmit immediately

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Collisions

- The remote side may send its frame before it hears the frame currently being sent
 - Both sides detect an idle line
 - Due to the propagation delay
- For A to detect the collision
 - Collisions can only be detected during transmission
 - $51.2\mu\text{s} \cdot 10\text{Mbps} = 64\text{ bytes}$



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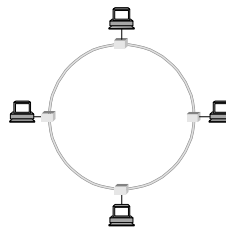
Upon Collision

- Send 32 jam bits, then stop transmitting frame
 - To ensure other hosts to detect collision
- minimum frame is 64 bytes (header + 46 bytes of data)
- delay and try again: exponential backoff
 - 1st time: 0 or 51.2us selected at random
 - 2nd time: 0, 51.2, or 102.4us
 - *n*th time: $k \times 51.2\text{us}$, for randomly selected $k=0..2^n - 1$
 - give up after several tries (usually 16)

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Token Ring

- Idea
 - Frames flow in one direction: upstream to downstream
 - special bit pattern (token) rotates around ring
 - must capture token before transmitting
 - release token after done transmitting
 - remove your frame when it comes back around
 - stations get round-robin service
- Lost Token
 - no token when initializing ring
 - bit error corrupts token pattern
 - node holding token crashes
- Generating a Token



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Wireless LANs

- IEEE 802.11
- Bandwidth: 1 - 11 Mbps
- Physical Media
 - diffused infrared (10m)
 - Diffused: the sender do not need a clear line of sight.
 - spread spectrum radio (2.4GHz): 11 Mbps \Rightarrow 54Mbps

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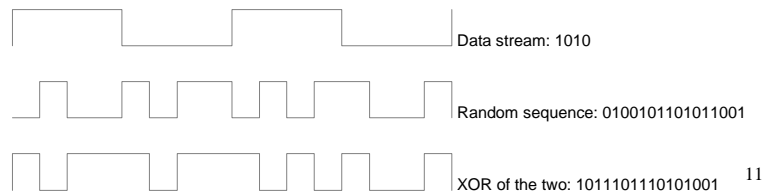
Spread Spectrum

- Idea
 - spread signal over wider frequency band than required
 - Minimize the impact of interference between different LANs
 - originally designed to thwart jamming
- Approach I: Frequency Hopping
 - transmit over random sequence of frequencies
 - sender and receiver share pseudorandom number generator and seed
 - 802.11 uses 79 x 1MHz-wide frequency bands

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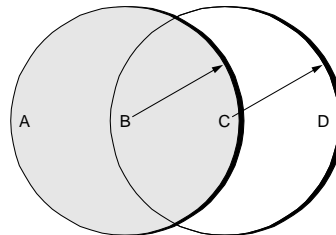
Spread Spectrum (cont)

- Approach II: Direct Sequence
 - for each bit, send XOR of that bit and n random bits
 - The receiver counts the number of 1s in each symbol
 - random sequence known to both sender and receiver
 - 802.11 defines an 11-bit chipping code
 - Requires a frequency band n times wider
 - The signal looks like noise to any receiver with different pseudorandom sequence



Collisions Avoidance

- Similar to Ethernet: Wait until link idle
- Problem: *hidden* and *exposed* nodes
 - $A \Rightarrow C; C \Rightarrow B;$
 - Collides at B
 - A, C cannot detect: hidden nodes
 - $B \Rightarrow A; C \Rightarrow D;$
 - C assumes collision
 - Actually no collision at A or D



- Cannot (listen) detect collision when transmit

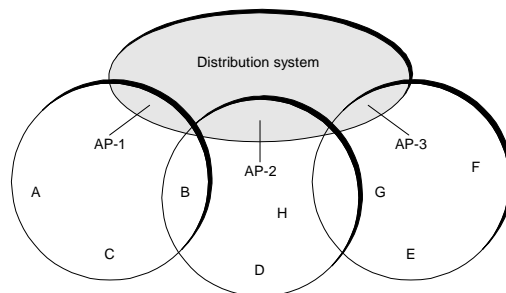
Multiple Access with Collision Avoidance (MACA)

- Sender transmits **RequestToSend (RTS)** frame
 - Specifying how long to hold the medium
- Receiver replies with **clearToSend (CTS)** frame
- Neighbors...
 - see CTS: keep quiet
 - see RTS but not CTS: receiver cannot hear me, ok to transmit
- Receiver sends **ACK** when has frame
 - neighbors silent until see ACK
- Collisions
 - no collisions detection
 - known when don't receive CTS or ACK
 - The cost of collision with RTS/CTS is much smaller
 - exponential backoff

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Supporting Mobility

- Case 1: *ad hoc* networking
- Case 2: *access points (AP)*
 - Tethered
 - each mobile node associates with an AP (base station)
 - Mobile nodes send to AP first; AP forwards



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Mobility (cont)

- Scanning (selecting an AP)
 - node sends **Probe** frame
 - all AP's w/in reach reply with **ProbeResponse** frame
 - node selects one AP; sends it **AssociateRequest** frame
 - AP replies with **AssociationResponse** frame
- When
 - active: when join or move
 - Signal with old AP weakened
 - new AP informs old AP via tethered network
 - passive: AP periodically sends **Beacon** frame