

Data Structures

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Binary Tree vs BST

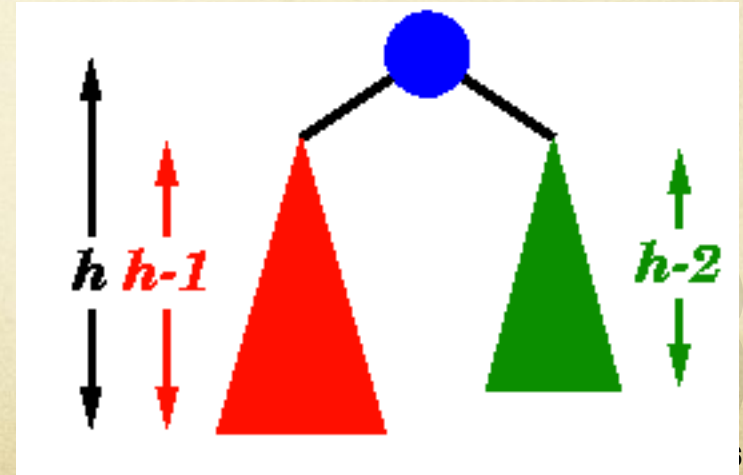
	BinaryTree	BinarySearchTree
insert(x)	$O(1)$	$O(h)$
remove(x)	$O(1)$	$O(h)$
contains(x)	$O(N)$	$O(h)$

- ◆ Main Problem:
 - ❑ Height of a BST, $h = O(n)$
 - ❑ A bad sequence of inserts can mess up the BST
 - ❑ OR, a bad sequence of deletes can mess up the BST
 - ❑ Making tree highly imbalanced and later searches very expensive

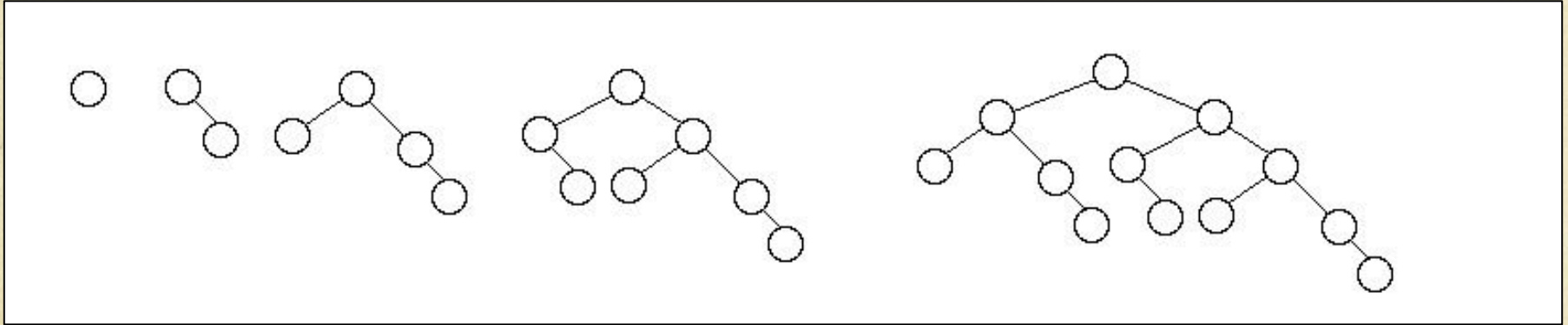
A good BST

- ◆ A good BST has height h as small as possible.
- ◆ **Fact:** A binary tree with height h has $\leq 2^h - 1$ nodes
- ◆ **Fact:** A binary tree with n nodes has height $\geq \log_2(n+1)$
- ◆ A good BST should have
 - height = $\text{ceil}(\log_2(n+1))$
 - Height of subtrees are equal
- ◆ **Redefine:** A good BST has
 - Heights of subtrees off by ≤ 1
 - at every node in tree
 - Problem: how to maintain it?

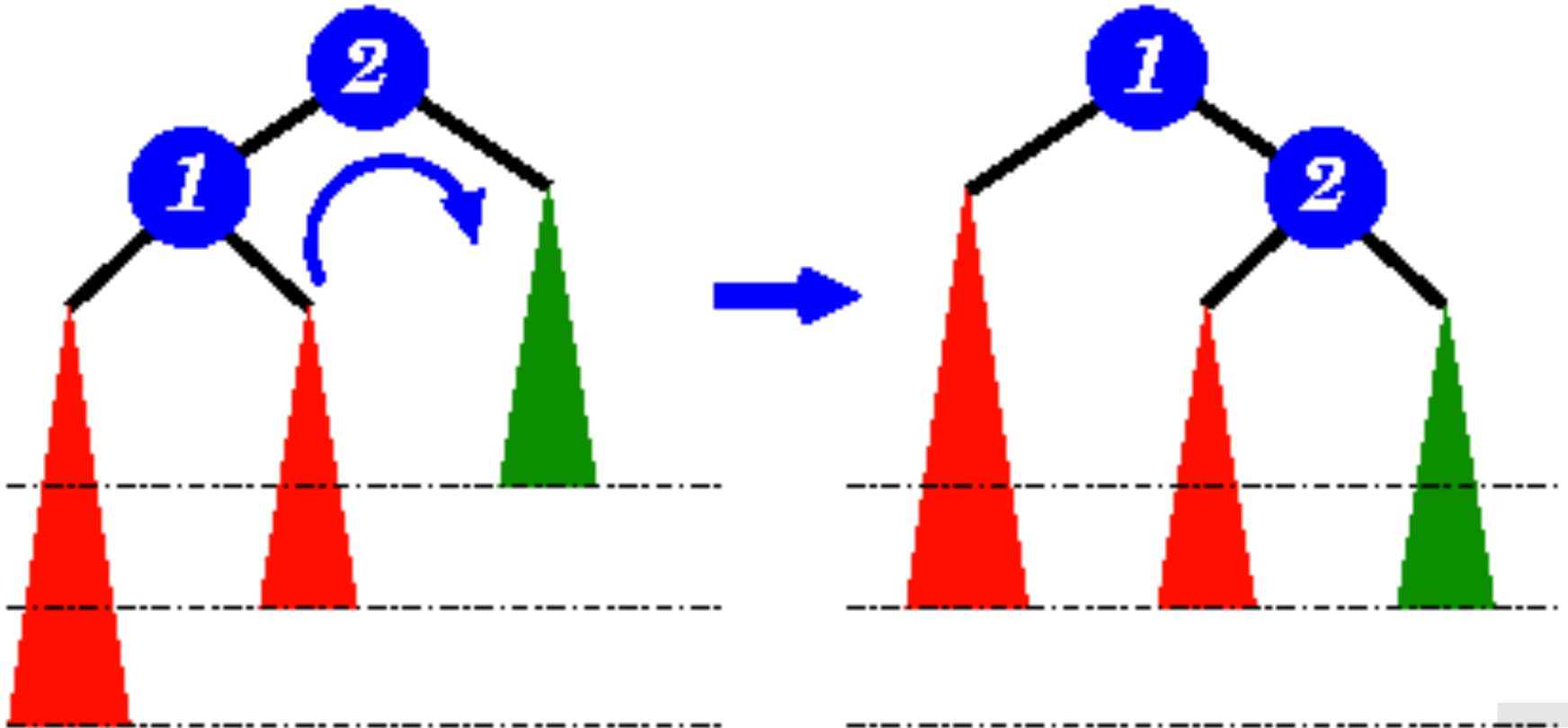
Does not work ... Why?



Worst-Case AVL Trees



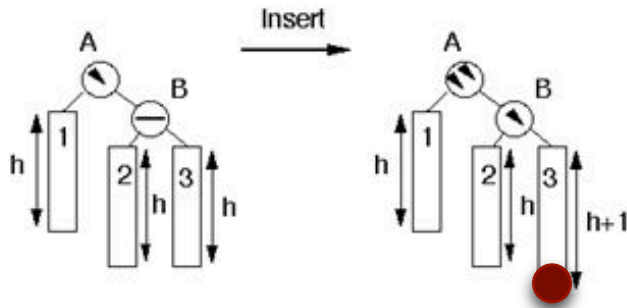
Rebalance on Imbalance



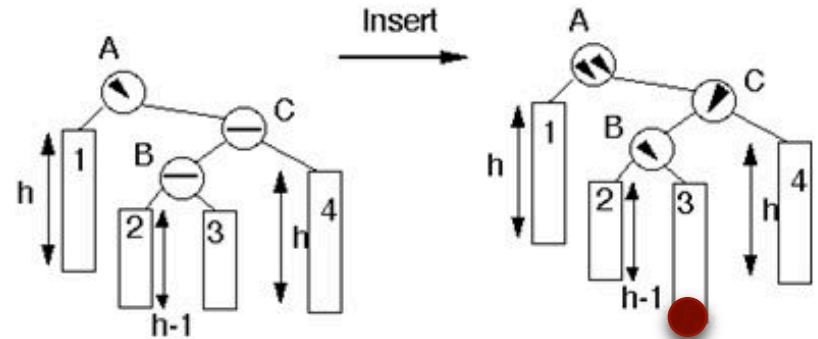
https://www.cs.auckland.ac.nz/~jmor159/PLDS210/fig/AVL_case1.gif

AVL Tree Insert

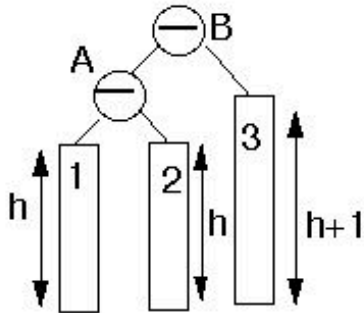
Insert into subtree 3



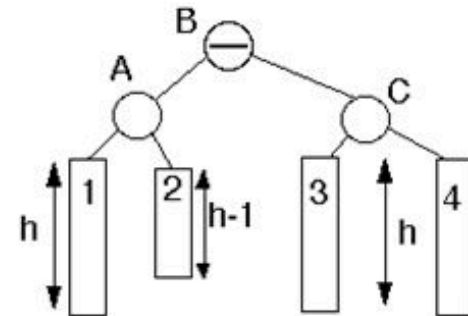
Insert into subtree 2 or 3



Perform single rotation



Perform double rotation

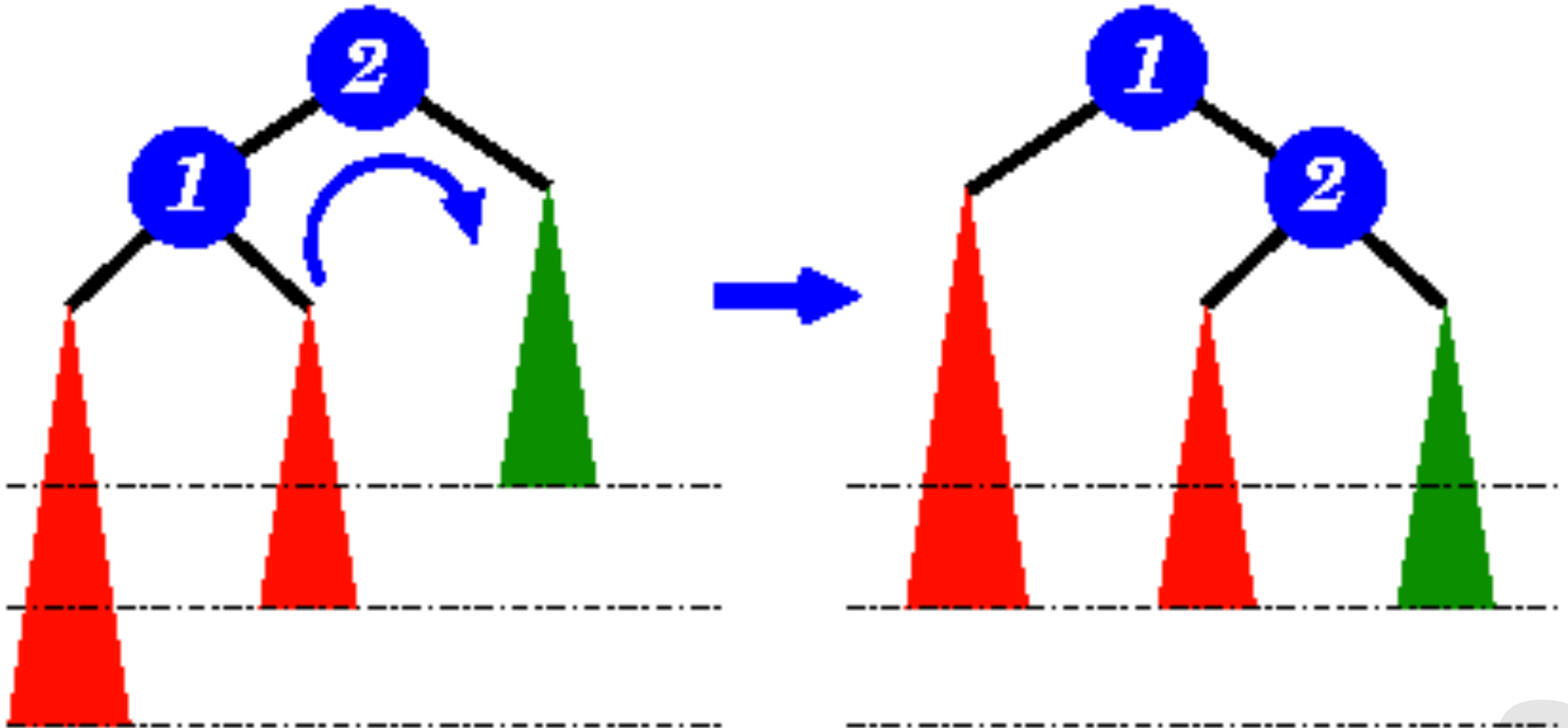


http://images.slideplayer.com/26/8338219/slides/slide_4.jpg

AVL Tree Animation

- ◆ Maintain balance info at every node
- ◆ Insert:
 - Insert into BST and then rebalance all nodes on the way to the root of the tree
 - <https://www.cs.usfca.edu/~galles/visualization/AVLtree.html>
- ◆ Delete:
 - Delete from BST and then rebalance all nodes on the way to the root of the tree
 - <https://www.cs.usfca.edu/~galles/visualization/AVLtree.html>
- ◆ Also <https://www.youtube.com/watch?v=FNeL18KsWPc>

Rebalance on Imbalance



https://www.cs.auckland.ac.nz/~jmor159/PLDS210/fig/AVL_case1.gif

AvlNode

```
private static class AvlNode<AnyType>
{
    // Constructors
    AvlNode( AnyType theElement )
    {
        this( theElement, null, null );
    }

    AvlNode( AnyType theElement, AvlNode<AnyType> lt, AvlNode<AnyType> rt )
    {
        element = theElement;
        left    = lt;
        right   = rt;
        height  = 0;
    }

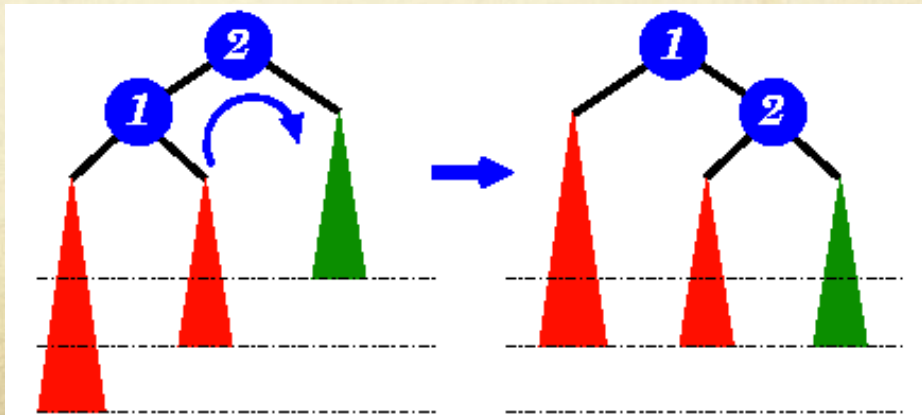
    AnyType      element;    // The data in the node
    AvlNode<AnyType> left;    // Left child
    AvlNode<AnyType> right;   // Right child
    int          height;     // Height
}
}
```

AVL Trees - same as BST

```
// *****PUBLIC OPERATIONS*****  
// void insert( x )      --> Insert x  
// void remove( x )     --> Remove x (unimplemented)  
// boolean contains( x ) --> Return true if x is present  
// boolean remove( x )  --> Return true if x was present  
// Comparable findMin( ) --> Return smallest item  
// Comparable findMax( ) --> Return largest item  
// boolean isEmpty( )   --> Return true if empty; else false  
// void makeEmpty( )   --> Remove all items  
// void printTree( )   --> Print tree in sorted order  
// *****ERRORS*****  
// Throws UnderflowException as appropriate
```

Single Rotation

```
private AvlNode<AnyType>
rotateWithLeftChild(AvlNode<AnyType> k2)
{
    AvlNode<AnyType> k1 = k2.left;
    k2.left = k1.right;
    k1.right = k2;
    k2.height = max(height(k2.left),height(k2.right)) + 1;
    k1.height = max( height( k1.left ), k2.height ) + 1;
    return k1;
}
```



Balance in AVL Trees

```
// Assume t is either balanced or within one of being balanced
private AvlNode<AnyType> balance( AvlNode<AnyType> t )
{
    if( t == null )
        return t;

    if( height( t.left ) - height( t.right ) > ALLOWED_IMBALANCE )
        if( height( t.left.left ) >= height( t.left.right ) )
            t = rotateWithLeftChild( t );
        else
            t = doubleWithLeftChild( t ); // double rotation
    else
        if( height( t.right ) - height( t.left ) > ALLOWED_IMBALANCE )
            if( height( t.right.right ) >= height( t.right.left ) )
                t = rotateWithRightChild( t );
            else
                t = doubleWithRightChild( t ); // double rotation

    t.height = Math.max( height( t.left ), height( t.right ) ) + 1;
    return t;
}
```

Insert in AVL Trees

```
public void insert(AnyType x) {root = insert( x, root ); } // non-recursive
private AvlNode<AnyType> insert( AnyType x, AvlNode<AnyType> t ) {
    // private recursive version of insert with extra parameter
    if( t == null ) // insert into empty tree; new node created
        return new AvlNode<>( x, null, null );

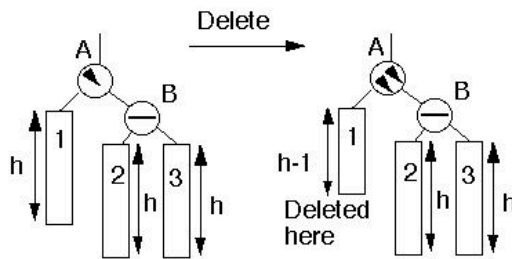
    int compareResult = x.compareTo( t.element );

    if( compareResult < 0 ) // insert into left subtree
        t.left = insert( x, t.left ); // add as left subtree after insertion
    else if( compareResult > 0 ) // insert into right subtree
        t.right = insert( x, t.right );
    else
        ; // Duplicate; do nothing (to be modified as needed)
    return balance( t ); // rebalance if needed
}
```

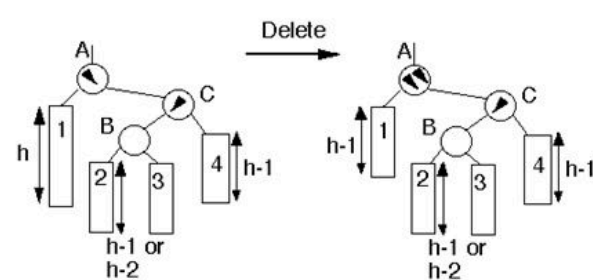
AVL Tree Deletion

AVL tree deletion examples

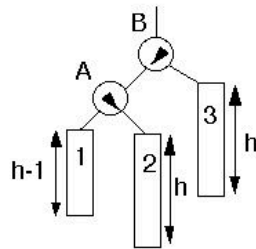
Deletion from subtree 1



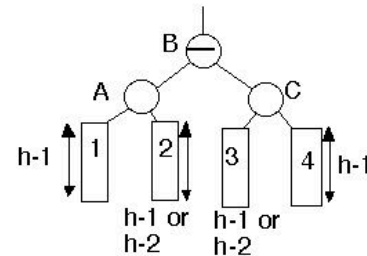
Deletion from subtree 1



Perform single rotation



Perform double rotation



http://images.slideplayer.com/26/8338219/slides/slide_5.jpg

Delete from AVL Tree

```
public void remove (AnyType x) {root = remove( x, root ); } // public non-recursive version
private AvlNode<AnyType> remove( AnyType x, AvlNode<AnyType> t ) {
    // private recursive version of insert with extra parameter
    if( t == null )
        return t; // Item not found; do nothing

    int compareResult = x.compareTo( t.element );

    if( compareResult < 0 )                // remove from left subtree
        t.left = remove( x, t.left );     // add as left subtree after removal
    else if( compareResult > 0 )          // remove from right subtree
        t.right = remove( x, t.right );
    else if( t.left != null && t.right != null ) // Two children
    {
        t.element = findMin( t.right ).element;
        t.right = remove( t.element, t.right );
    }
    else                                  // At most one child - easy case
        t = ( t.left != null ) ? t.left : t.right;
    return balance( t );                  // rebalance if needed
}
```

Major Difference: AVL - BST

- ◆ Height of BST Tree = $h = O(n)$
- ◆ Height of AVL Tree = $h = O(\log n)$

	BST	AVL Trees
insert(x)	$O(h)$	$O(\log N)$
remove(x)	$O(h)$	$O(\log N)$
contains(x)	$O(h)$	$O(\log N)$

Static vs Dynamic Structures

Time Complexity of List Operations

	ArrayList	LinkedList
get(idx)	O(1)	O(N)
set(idx, x)	O(1)	O(N)
add(idx,x)	O(N)	O(N)
remove(idx)	O(N)	O(N)
addBefore(p,x)		O(1)
Remove(p)		O(1)

Linear Data Structures

◆ Lists

- ArrayList
- LinkedList

◆ Stacks & Queues

◆ Sorted Lists

- List is sorted according to some key value in the data
- Inserts and deletes must maintain sorted order
- Search is an important operation
- Implementations
 - ArrayList
 - LinkedList

SortedList: Time Complexity

	ArrayList	LinkedList
add(x)	O(N)	O(N)
remove(x)	O(N)	O(N)
find(x)	O(log N)	O(N)

	ArrayList	LinkedList
add(x) after find(x)	O(N)	O(1)
remove(x) after find(x)	O(N)	O(1)
find(x)	O(log N)	O(N)

Tradeoffs!

	BinaryTree	BinarySearchTree	AVL Trees
insert(x)	O(1)		O(log N)
remove(x)	O(1)		O(log N)
contains(x)	O(N)		O(log N)

Static vs Dynamic Structures

- ◆ Static data structures
 - ❑ Build data structures once
 - ❑ Assume no (or few) updates and lots of queries
 - ❑ Use Static Structure such as SortedList or BST
- ◆ Dynamic data structures
 - ❑ Data structure with lots of updates and no/few queries
 - Stacks and queues
 - ❑ Data structure with lots of updates & lots of queries
 - ❑ Answers to queries depends on current state
 - ❑ E.g., Stacks and Queues