

Data Structures

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Sorting

- ◆ Putting items in any order
- ◆ Items need to be "comparable"
- ◆ Need to know how to "compare"
- ◆ Results of compare need to be "definitive" (YES/NO/EQUAL)

Complexity Measures

- ◆ Number of **Comparisons** made
- ◆ Number of **Data Movements** made

Inefficient Sorting Algorithms

Selection Sort

- ◆ Repeatedly **select** the next smallest item and place it in right location
- ◆ **Invariant**: After **k** iterations first **k** smallest items are in right location
- ◆ In iteration **k**, find smallest item in locations **k .. n** and swap it with item in location **k**
- ◆ Time complexity of iteration **k** is $O(n-k)$
- ◆ Total time complexity = $(n-1) + (n-2) + \dots + 1 = O(n^2)$

Insertion Sort

- ◆ Repeatedly **insert** next item into "growing" sorted list
- ◆ **Invariant**: After **k** iterations the first **k** locations are in sorted order
- ◆ In iteration **k**, insert item in location **k** into sorted sublist in locations **1 .. k-1**
- ◆ Time complexity of iteration **k** is $O(k)$
- ◆ Total time complexity = $1 + 2 + \dots + (n-2) + (n-1) = O(n^2)$

Figure 8.3

Basic action of insertion sort (the shaded part is sorted)

Array Position	0	1	2	3	4	5
Initial State	8	5	9	2	6	3
After $a[0..1]$ is sorted	5	8	9	2	6	3
After $a[0..2]$ is sorted	5	8	9	2	6	3
After $a[0..3]$ is sorted	2	5	8	9	6	3
After $a[0..4]$ is sorted	2	5	6	8	9	3
After $a[0..5]$ is sorted	2	3	5	6	8	9

Figure 8.4

A closer look at the action of insertion sort (the dark shading indicates the sorted area; the light shading is where the new element was placed).

Array Position	0	1	2	3	4	5
Initial State	8	5				
After $a[0..1]$ is sorted	5	8	9			
After $a[0..2]$ is sorted	5	8	9	2		
After $a[0..3]$ is sorted	2	5	8	9	6	
After $a[0..4]$ is sorted	2	5	6	8	9	3
After $a[0..5]$ is sorted	2	3	5	6	8	9

Insertion Sort

```
public static <AnyType extends Comparable<? super AnyType>>
void insertionSort( AnyType [ ] a )
{
    int j;

    for( int p = 1; p < a.length; p++ )
    {
        AnyType tmp = a[ p ];
        for( j = p; j > 0 && tmp.compareTo( a[ j - 1 ] ) < 0; j-- )
            a[ j ] = a[ j - 1 ];
        a[ j ] = tmp;
    }
}
```

Bubble Sort

- ◆ Repeatedly **bubble** smaller items “upward”
- ◆ **Invariant**: After **k** iterations the first **k** locations are in sorted order
- ◆ In iteration **k**, scan entire list from end comparing adjacent items along the way and swapping if they are out of order
- ◆ Time complexity of iteration **k** is $O(n)$
- ◆ Total time complexity = $n(n-1) = O(n^2)$

ShellSort: Sophisticated Insertion Sort

Idea: Make “sublists” and sort them using insertion sort

Figure 8.5

Shellsort after each pass if the increment sequence is {1, 3, 5}

ORIGINAL	81	94	11	96	12	35	17	95	28	58	41	75	15
After 5-sort	35	17	11	28	12	41	75	15	96	58	81	94	95
After 3-sort	28	12	11	35	15	41	58	17	94	75	81	96	95
After 1-sort	11	12	15	17	28	35	41	58	75	81	94	95	96

ShellSort

```
public static <AnyType extends Comparable<? super AnyType>>
    void shellsort( AnyType [ ] a )
    {
        int j;

        for( int gap = a.length / 2; gap > 0; gap /= 2 )
            for( int i = gap; i < a.length; i++ )
                {
                    AnyType tmp = a[ i ];
                    for( j = i; j >= gap &&
                        tmp.compareTo( a[ j - gap ] ) < 0; j -= gap )
                        a[ j ] = a[ j - gap ];
                    a[ j ] = tmp;
                }
    }
```

Improved Sorting Algorithms

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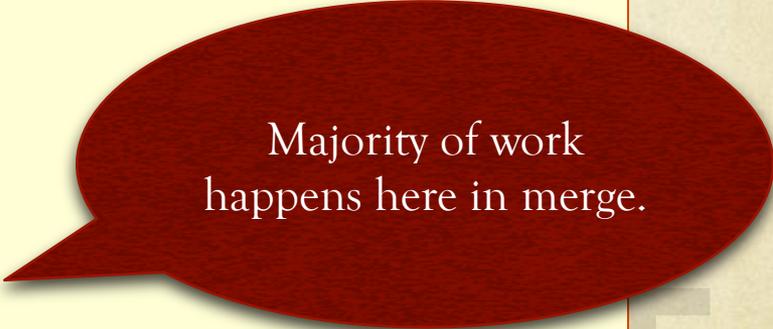
Divide and Conquer

- ◆ Divide the work into smaller subproblems by partitioning
- ◆ Sort each partition separately
- ◆ Merge sorted sublists

Merge Sort

```
public static <AnyType extends Comparable<? super AnyType>>
    void mergeSort( AnyType [ ] a ) {
        AnyType [ ] tmpArray = (AnyType[]) new Comparable[ a.length ];
        mergeSort( a, tmpArray, 0, a.length - 1 );
    }
```

```
private static <AnyType extends Comparable<? super AnyType>>
    void mergeSort( AnyType [ ] a, AnyType [ ] tmpArray,
        int left, int right )
    {
        if( left < right )
        {
            int center = ( left + right ) / 2;
            mergeSort( a, tmpArray, left, center );
            mergeSort( a, tmpArray, center + 1, right );
            merge( a, tmpArray, left, center + 1, right );
        }
    }
```



Majority of work
happens here in merge.

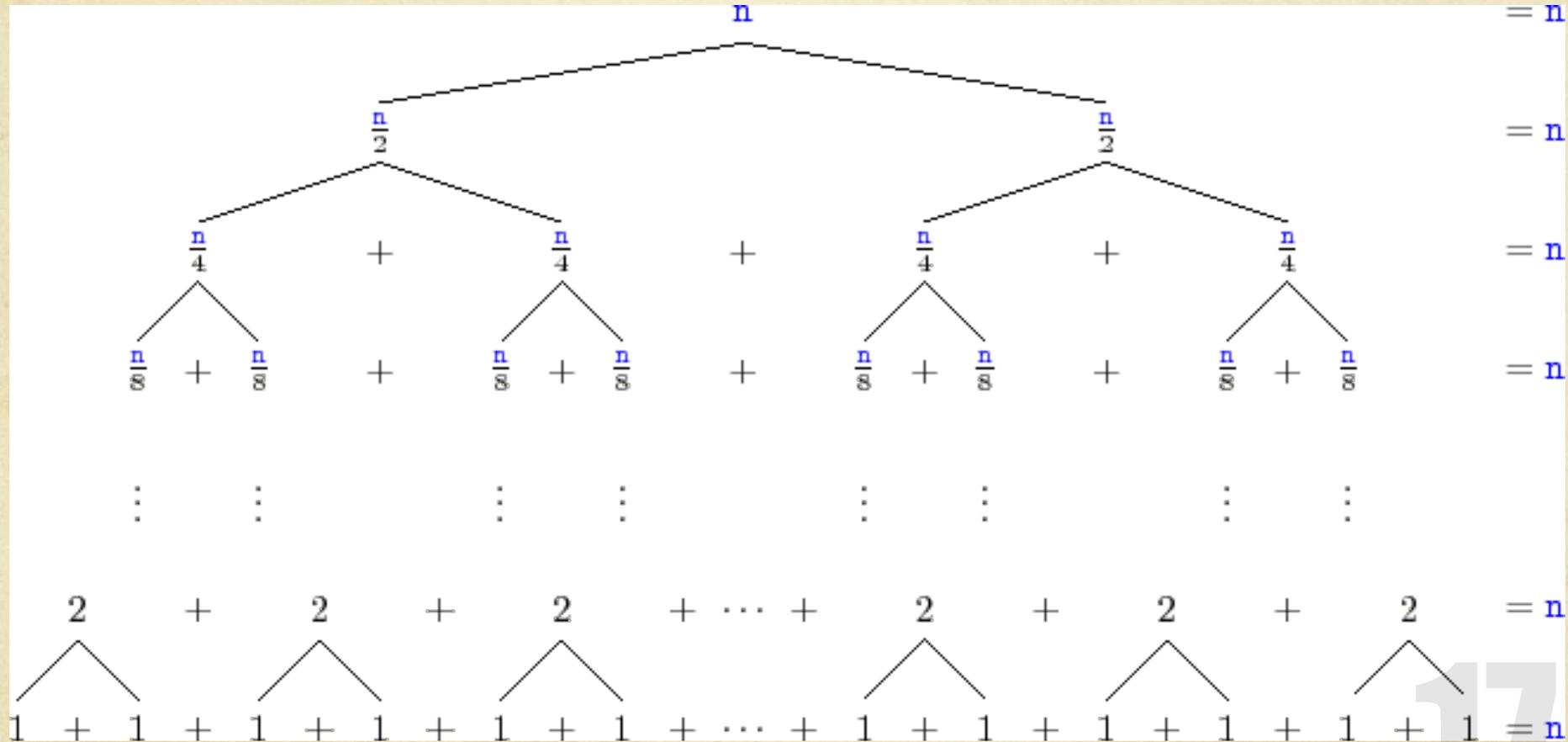
Merge in Merge Sort

```
private static <AnyType extends Comparable<? super AnyType>>
void merge( AnyType[ ] a, AnyType[ ] tmpArray, int leftPos, int rightPos, int rightEnd )
{
    int leftEnd = rightPos - 1;
    int tmpPos = leftPos;
    int numElements = rightEnd - leftPos + 1;
    while( leftPos <= leftEnd && rightPos <= rightEnd )
        if( a[ leftPos ].compareTo( a[ rightPos ] ) < 0 )
            tmpArray[ tmpPos++ ] = a[ leftPos++ ];
        else
            tmpArray[ tmpPos++ ] = a[ rightPos++ ];
    while( leftPos <= leftEnd ) // Copy rest of first half
        tmpArray[ tmpPos++ ] = a[ leftPos++ ];
    while( rightPos <= rightEnd ) // Copy rest of right half
        tmpArray[ tmpPos++ ] = a[ rightPos++ ];

    for( int i = 0; i < numElements; i++, rightEnd-- )
        a[ rightEnd ] = tmpArray[ rightEnd ];
}
```

Time Complexity:
 $O(L_a + L_b)$

Analysis: Recursion Tree



<http://opendatastructures.org/versions/edition-0.1c/ods-java/img1231.png>

Alternative Analysis

- ◆ Let $T(n)$ = time complexity of MergeSort on list with n elements
- ◆ We know that time complexity of merge operation on two sorted lists of total length n is $O(n)$
- ◆ We can write a **recurrence relationship** as follows:
 - $T(n) = T(n/2) + T(n/2) + O(n)$

$$T(n) = 2T(n/2) + O(n)$$

◆ Expansion Method:

$$T(n) = 2T(n/2) + O(n)$$

$$T(n) \leq 2T(n/2) + cn$$

$$T(n) \leq 2(2T(n/4) + cn/2) + cn$$

$$T(n) \leq 4T(n/4) + 2cn$$

$$T(n) \leq 4(2T(n/8) + cn/4) + 2cn$$

$$T(n) \leq 8T(n/8) + 3cn$$

...

$$T(n) \leq nT(1) + (\log n) cn$$

$$T(n) = O(n \log n)$$

Use "Guestimations"

- ◆ Guess that $T(n) = O(n) \leq cn$
 - Then we know that $T(n/2) = cn/2$
 - Right side = $2(cn/2) + c_1n = cn + c_1n$
 - Since both c and $c_1 > 0$, we cannot make right side $\leq cn$
 - **Failure!**
- ◆ Guess that $T(n) = O(n^2) \leq cn^2$
 - Then we know that $T(n/2) \leq c(n/2)^2$
 - Right side = $2(cn^2/4) + c_1n = cn^2/2 + c_1n$
 - We can make right side $\leq cn^2$ by choosing c large enough
 - But was our choice too liberal?

Use "Guestimations" ... 2

- ◆ Guess that $T(n) = O(n \log n) \leq c (n \log n)$
 - Then we know that $T(n/2) \leq c(n/2) \log (n/2)$
 - Right side
 - $= 2(c(n/2) \log (n/2)) + c_1 n$
 - $= cn (\log n - 1) + c_1 n$
 - $= c (n \log n) + (c_1 - c)n$
 - We can make right side $\leq c (n \log n)$ by choosing $c > c_1$
- ◆ Thus $T(n) = O(n \log n)$ is the best solution among three choices

More general recurrences

- ◆ $T(n) = a T(n/b) + f(n)$
 - $T(n) = O(n \log n)$, if $a = b$ and $f(n) = \Theta(n)$
 - $T(n) = \Theta(n^{\{\log_b a\}})$, if $f(n) = O(n^{\{\log_b a - \epsilon\}})$

Important
Case

HeapSort

- ◆ Discussed earlier
- ◆ Time Complexity = $O(n \log n)$

QuickSort

- ◆ Carefully divide, then conquer
- ◆ First partition into **Small** and **Large** sets, then call recursively on each of the sets and concatenate two sorted sublists
- ◆ Since we partition first, "merge" is not necessary; only need to concatenate two sorted lists

Figure 8.10 Quicksort

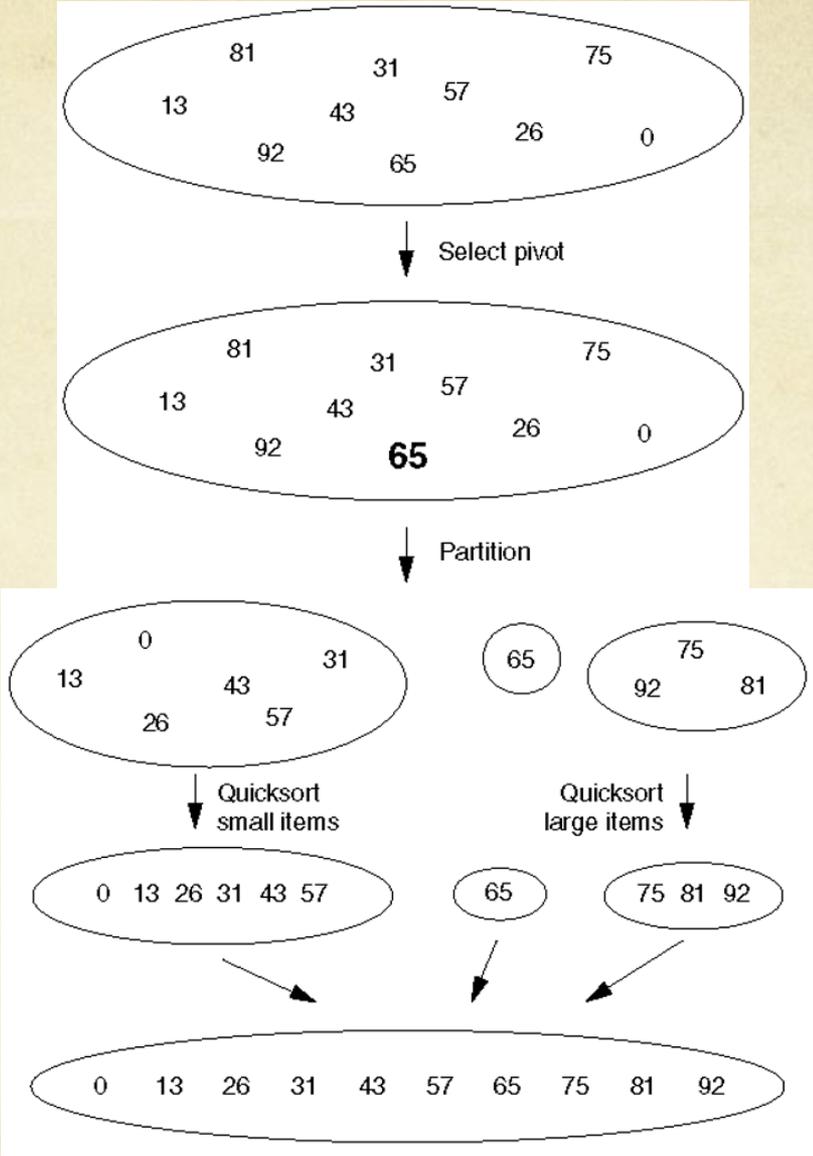


Figure 8.11 Partitioning algorithm: Pivot element 6 is placed at the end.

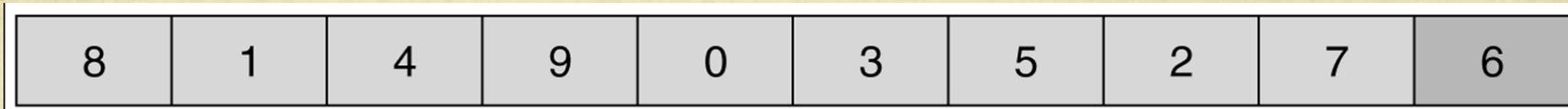


Figure 8.12 Partitioning algorithm: i stops at large element 8; j stops at small element 2.

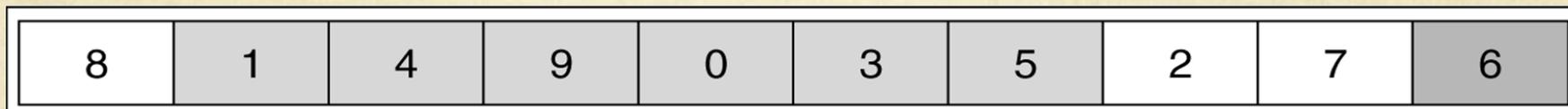


Figure 8.13 Partitioning algorithm: The out-of-order elements 8 and 2 are swapped.

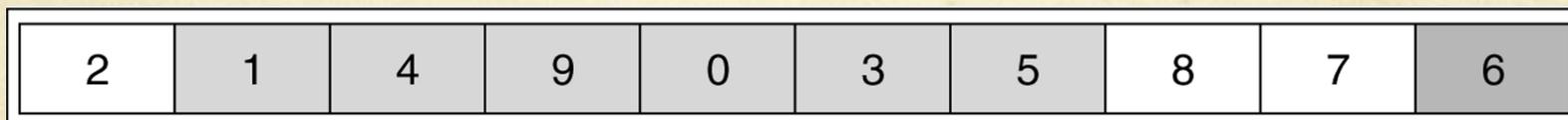


Figure 8.14 Partitioning algorithm: i stops at large element 9; j stops at small element 5.

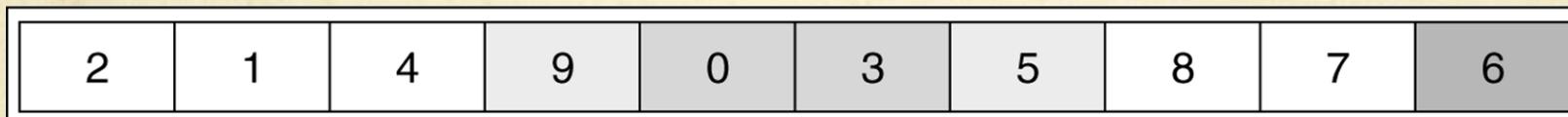


Figure 8.15 Partitioning algorithm: The out-of-order elements 9 and 5 are swapped.

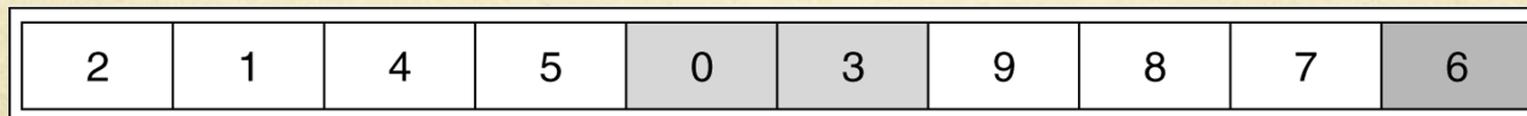


Figure 8.16 Partitioning algorithm: i stops at large element 9; j stops at small element 3.

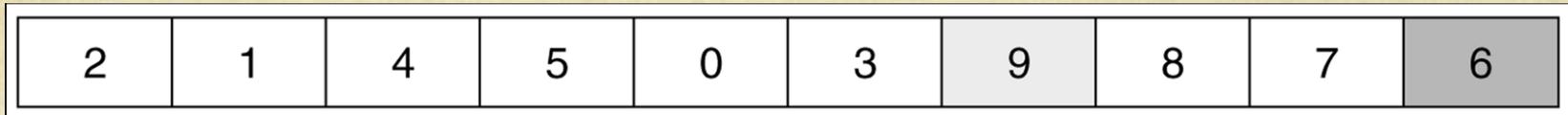


Figure 8.17 Partitioning algorithm: Swap pivot and element in position i.

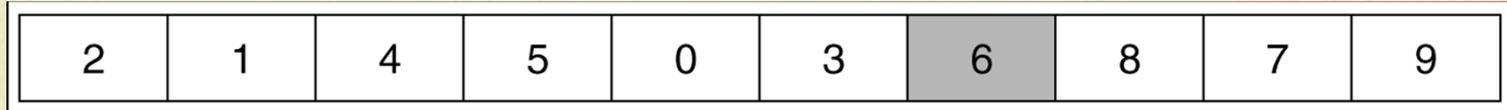


Figure 8.18 Original array

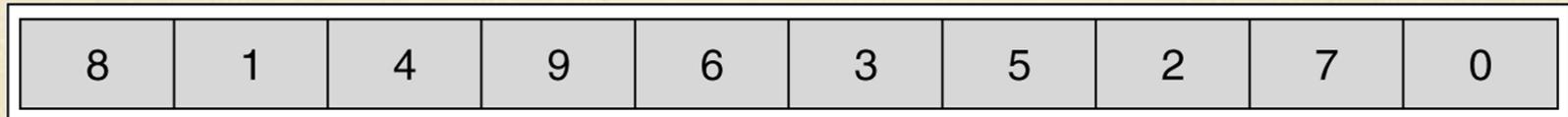


Figure 8.19 Result of sorting three elements (first, middle, and last)

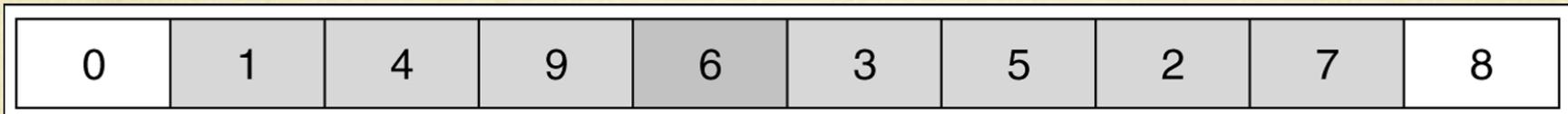
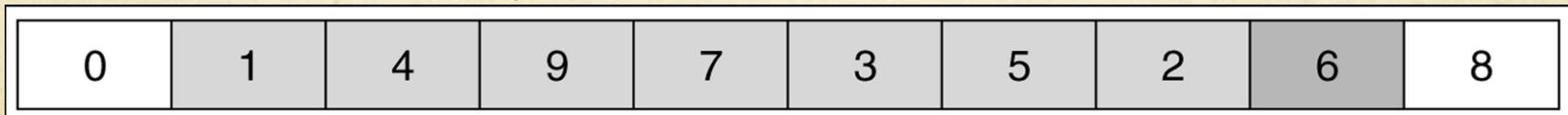


Figure 8.20 Result of swapping the pivot with the next-to-last element



Quicksort

```
public static <AnyType extends Comparable<? super AnyType>> void quicksort(AnyType [ ] a
    { quicksort( a, 0, a.length - 1 ); }

private static <AnyType extends Comparable<? super AnyType>>
void quicksort(AnyType [ ] a, int left, int right ) {
    if( left + CUTOFF <= right ) {
        AnyType pivot = median3( a, left, right );

        // Begin partitioning
        int i = left, j = right - 1;
        for(;;) {
            while( a[ ++i ].compareTo( pivot ) < 0 ) {}
            while( a[ --j ].compareTo( pivot ) > 0 ) {}
            if( i < j )
                swapReferences( a, i, j );
            else
                break;
        }
        swapReferences( a, i, right - 1 ); // Restore pivot
        quicksort( a, left, i - 1 ); // Sort small elements
        quicksort( a, i + 1, right ); // Sort large elements
    }
    else // Do an insertion sort on the subarray
        insertionSort( a, left, right );
}
```

Upper and Lower Bounds

- ◆ Upper bound on time complexity of sorting is $O(n \log n)$, because there exists at least one algorithm that runs in time $O(n \log n)$ in the worst case.
- ◆ But is this the best possible?
- ◆ Lower bound on the time complexity of a problem is $T(n)$ if \forall algorithms that solve the problem, their time complexity is $\Omega(T(n))$.
- ◆ It can be mathematically proved that lower bound for sorting is $\Omega(n \log n)$.
- ◆ Thus Merge Sort and Heap Sort are **optimal**.

Special Sorting Algorithms

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Bucket Sort

- ◆ N **integer** values in the range $[a..a+m-1]$
- ◆ For e.g., sort a list of 50 scores in the range $[0..9]$.
- ◆ **Algorithm**
 - Make m buckets $[a..a+m-1]$
 - As you read elements throw into appropriate bucket
 - Output contents of buckets $[0..m]$ in that order
- ◆ **Time $O(N+m)$**
- ◆ **Warning: This algorithm cannot be used for “infinite-precision” real numbers, even if the range of values is specified.**

Stable Sort

- ◆ A sorting algorithm is **stable** if equal elements appear in the same order in both the input and the output.
- ◆ Which sorts are stable? Homework!

Radix Sort



Algorithm

for $i = 1$ **to** d **do**

sort array A on digit i using any sorting algorithm

Time Complexity: $O((N+m) + (N+m^2) + \dots + (N+m^d))$

Space Complexity: $O(m^d)$

Improved Radix Sort



Algorithm

for $i = d$ to 1 do

sort array A on digit i using a stable sort algorithm

Time Complexity: $O((n+m)d)$

•Warning: This algorithm cannot be used for “infinite-precision” real numbers, even if the range of values is specified.

Counting Sort

Initial Array

1	2	3	4	5	6	7	8
2	5	3	0	2	3	0	3

Counts

0	1	2	3	4	5
2	0	2	3	0	1

Cumulative
Counts

0	1	2	3	4	5
2	2	4	7	7	8

Time Complexity: $O(n+C)$

•Warning: This algorithm cannot be used for “infinite-precision” real numbers, even if the range of values is specified.

Sorting Algorithms Summary

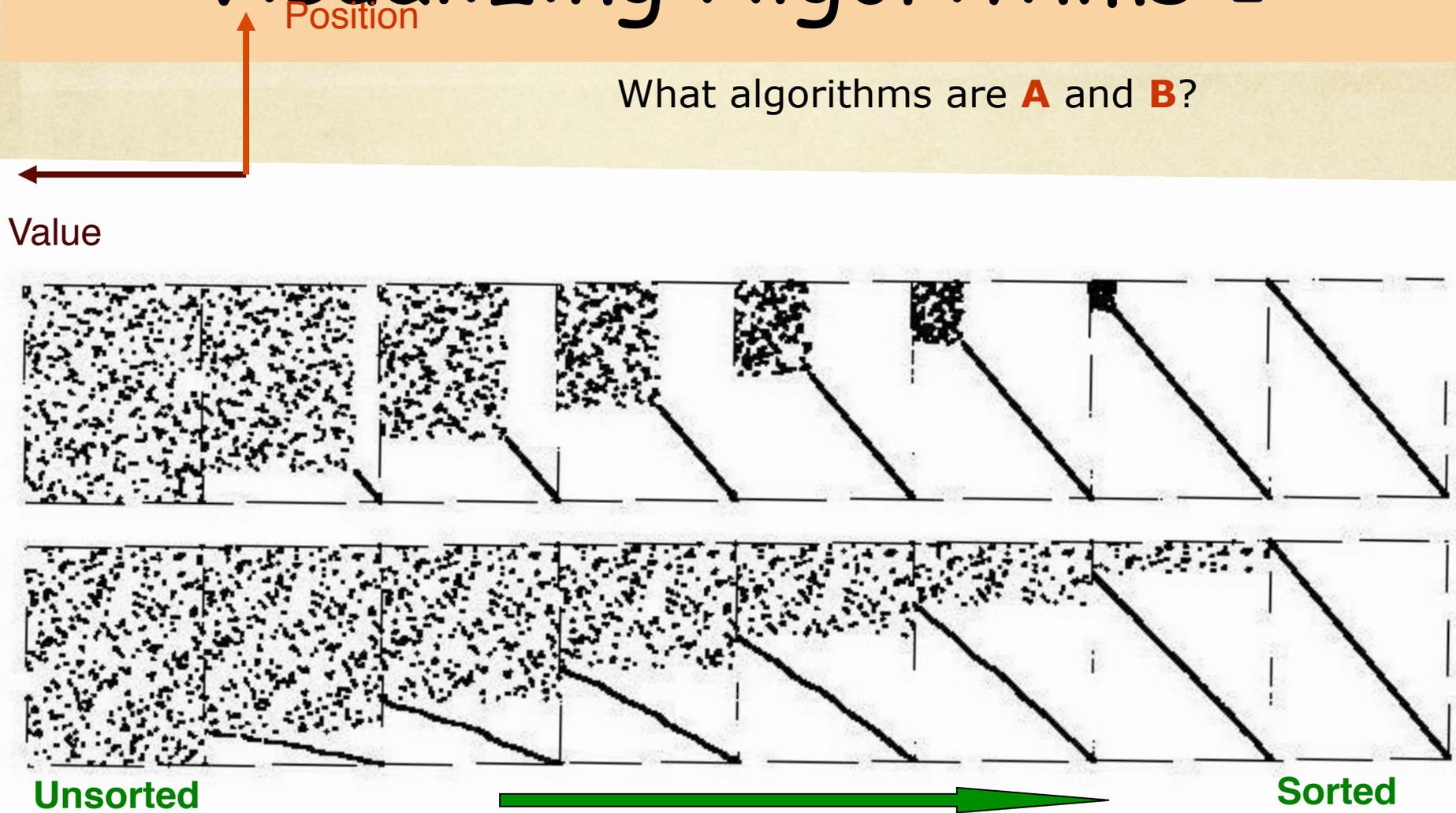
- ◆ $O(n^2)$ sorting algorithms
 - Selection Sort
 - Insertion Sort
 - Bubble Sort & Shaker Sort
- ◆ $O(n^2)$ sorting algorithms, but $O(n \log n)$ on average
 - Quick Sort
- ◆ $O(n^2)$ sorting algorithms
 - Shell Sort
- ◆ $O(n \log n)$ sorting algorithms
 - Merge Sort
 - Heap Sort
- ◆ $O(n)$ specialized sorting algorithms
 - Bucket and Radix Sort
 - Counting Sort

Visualizing Sorting

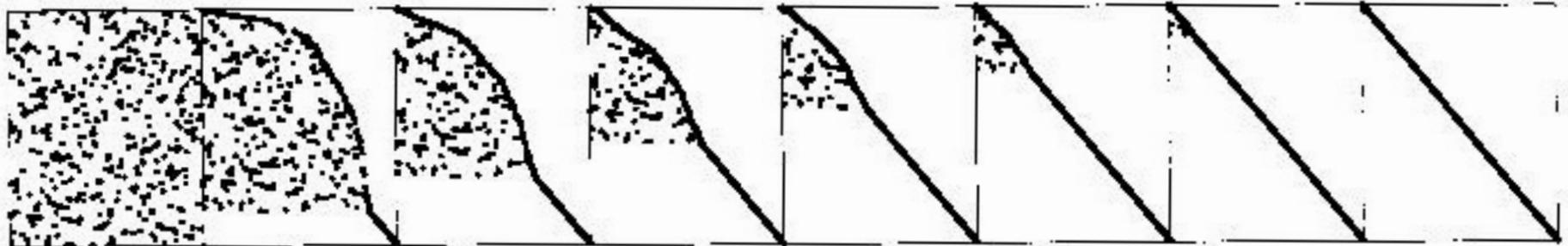
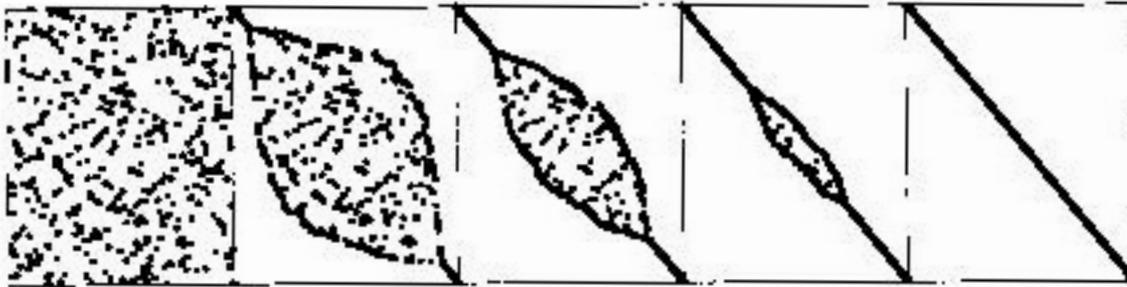
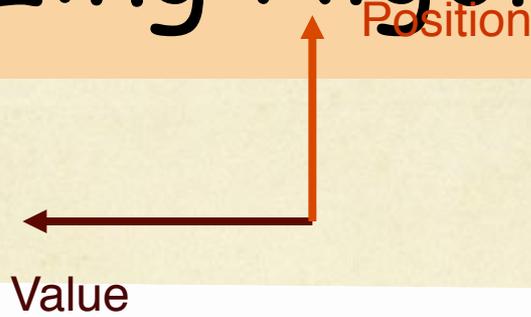
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Visualizing Algorithms 1

What algorithms are **A** and **B**?



Visualizing Algorithms 2

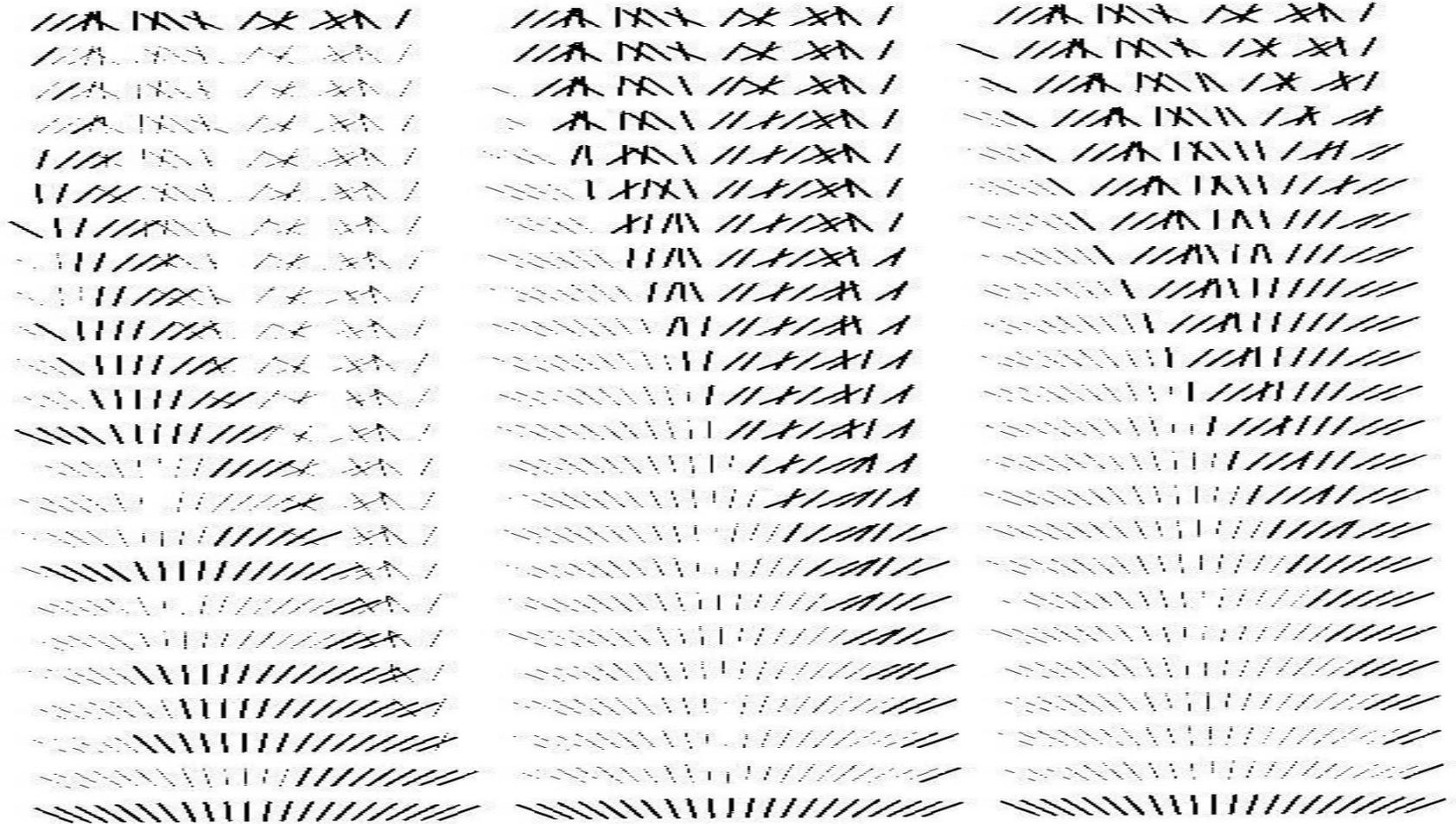


Unsorted



Sorted

Visualizing Comparisons 3



Animations (Not sure which work)

- ◆ <http://cg.scs.carleton.ca/~morin/misc/sortalg/>
- ◆ <http://home.westman.wave.ca/~rhenry/sort/>
- ◆ time complexities on best, worst and average case
- ◆ <http://vision.bc.edu/~dmartin/teaching/sorting/anim-html/quick3.html>
- ◆ runs on almost sorted, reverse, random, and unique inputs; shows code with invariants
- ◆ <http://www.brian-borowski.com/Sorting/>
- ◆ comparisons, movements & stepwise animations with user data
- ◆ <http://maven.smith.edu/~thiebaut/java/sort/demo.html>
- ◆ comparisons & data movements and step by step execution

Optional Topics

- ◆ Lower Bound for Sorting
 - Needs to decide which of $n!$ perms is the right answer
 - Each comparison can only separate two subsets and the whole process requires $\Omega(\log(n!))$
 - $\Omega(n \log n)$
- ◆ External Sorting Algorithms

External Sorting Methods

- ◆ Assumptions:
 - data is too large to be held in main memory;
 - data is read or written in blocks;
 - 1 or more external devices available for sorting
- ◆ Sorting in main memory is cheap or free
- ◆ Read/write costs are the dominant cost
- ◆ Wide variety of storage types and costs
- ◆ No single strategy works for all cases

External Merge Sort

- ◆ Initial distribution pass
- ◆ Several multi-way merging passes

ASORTINGANDMERGINGEXAMPLEWITHFORTYFIVERECORDS.\$

AOS.DMN.AEX.FHT.ERV.\$

IRT.EGR.LMP.ORT.CEO.\$

AGN.GIN.EIW.FIY.DRS.\$

AAGINORST.FFHIORTTY.\$

DEGGIMNR.CDEEORRSV.\$

AEEILMPWX.\$

AAADEEEGGGIIILMMNNOPRRSTWX.\$

CDEEFFHIOORRRSTTVY.\$

AAACDDEEEEEFFGGGHHIIILMMNNOC

With $2P$ external devices
Space for M records in main memory
Sorting N records needs
 $1 + \log_p(N/M)$ passes