## Sorting Algorithms

- Number of Comparisons
- Number of Data Movements
- Additional Space Requirements



**Figure 2.4** The operation of merge sort on the array  $A = \langle 5, 2, 4, 7, 1, 3, 2, 6 \rangle$ . The lengths of the sorted sequences being merged increase as the algorithm progresses from bottom to top.



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```
MERGE(A, p, q, r)
 1 n_1 \leftarrow q - p + 1
 2 n_2 \leftarrow r - q
 3 create arrays L[1 \dots n_1 + 1] and R[1 \dots n_2 + 1]
 4 for i \leftarrow 1 to n_1
 5
           do L[i] \leftarrow A[p+i-1]
 6
    for j \leftarrow 1 to n_2
                                                 Assumption: Array
 7
           do R[j] \leftarrow A[q+j]
 8 L[n_1+1] \leftarrow \infty
                                                 A is sorted from
 9
    R[n_2+1] \leftarrow \infty
                                                 positions p to q
10 \quad i \leftarrow 1
                                                 and also from
11 j \leftarrow 1
                                                 positions q+1 to r.
12 for k \leftarrow p to r
13
           do if L[i] \leq R[j]
                                                            O(n)
14
                  then A[k] \leftarrow L[i]
15
                        i \leftarrow i + 1
16
                  else A[k] \leftarrow R[j]
17
                        i \leftarrow i+1
                                                                    4
```

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```
MERGE-SORT(A, p, r)

1 if p < r

2 then q \leftarrow \lfloor (p+r)/2 \rfloor

3 MERGE-SORT(A, p, q)

4 MERGE-SORT(A, q+1, r)

5 MERGE(A, p, q, r)
```



**Figure 2.5** The construction of a recursion tree for the recurrence T(n) = 2T(n/2) + cn. Part (a) shows T(n), which is progressively expanded in (b)–(d) to form the recursion tree. The fully expanded tree in part (d) has  $\lg n + 1$  levels (i.e., it has height  $\lg n$ , as indicated), and each level contributes a total cost of cn. The total cost, therefore, is  $cn \lg n + cn$ , which is  $\Theta(n \lg n)$ .

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#### Figure 8.10 Quicksort



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#### Last step of Partition

Figure A If 6 is used as pivot, the end result after partitioning is as shown in the Figure B.



Figure B Result after Partitioning

	2	1	4	5	0	3	6	8	7	9	

#### QuickSort

QUICKSORT(array A, int p, int r) if (p < r)1  $\mathbf{2}$ then  $q \leftarrow \text{PARTITION}(A, p, r)$ QUICKSORT(A, p, q-1)3 QUICKSORT(A, q+1, r)4

To sort array call QUICKSORT(A, 1, length[A]).

PARTITION(array A, int p, int r)

#### Problems with QuickSort

- Bad pivot choices can lead to worst-case behavior of  $O(n^2)$
- High cost of recursive calls
- Unstable sorting algorithm
- Lots of potential data movements.

### Suggestions for improvement

- Improved choice of pivot to improve worst-case time complexity
  - Randomly choose pivot
  - Pick median of three choices (deterministic or random)
- Huge cost incurred by recursive calls especially when the sublists get smaller and smaller
  - When the sublist becomes smaller than some threshold, call InsertionSort or some other non-recursive sorting algorithm

#### Questions to ask

- Worst-case versus average-case behavior of the sorting algorithms
- Why is QuickSort fast in practice as opposed to others?
- How can we improve on it?
- How is it different from the divide-and-conquer algorithm, MergeSort?

# Sorting Algorithms

- SelectionSort
- InsertionSort
- BubbleSort
- ShakerSort
- QuickSort
- MergeSort
- HeapSort
- Bucket & Radix Sort
- Counting Sort

#### Problems to think about!

- What is the least number of comparisons you need to sort a list of 3 elements? 4 elements? 5 elements?
- How to arrange a tennis tournament in order to find the tournament champion with the least number of matches? How many tennis matches are needed?