

# Introduction to Data Science

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# Streams & Bloom Filters

# Moments

- ▶ i-th Moment
- ▶ Zeroth Moment: Count of distinct elements in stream
- ▶ First Moment: Count of elements in stream, i.e., Size of stream; sum of freq
- ▶ Second Moment: Sum of squares of frequencies
- ▶ Average = ?
- ▶ Variance = ?

$$\frac{1}{m} \sum_{s=1}^m \left( f_s - \frac{n}{m} \right)^2 = \frac{1}{m} \sum_{s=1}^m \left( f_s^2 - 2 \frac{n}{m} f_s + \left( \frac{n}{m} \right)^2 \right) = \left( \frac{1}{m} \sum_{s=1}^m f_s^2 \right) - \frac{n^2}{m^2}$$

# Sampling Woes

- ▶ **Stream**: Tuples (**user, query, time**); **Sampling**: 1 in 10
  - ❑ Each user has 1/10 of their queries processed
- ▶ **Query**: Fraction of typical user's queries repeated over last month
- ▶ **Correct Answer**: Suppose user has  $s$  unique queries and  $d$  queries twice and NO queries more than twice in the last month; Answer =  $d/(s+d)$
- ▶ **Problem**: Reported fraction would be wrong
  - ❑ In the sampled stream,  $s/10$  are unique queries and  $d/100$  queries appear twice
  - ❑ The remainder of the queries that should appear twice will appear once  $18d/100$
  - ❑ We will report  $d/(10s + 19d)$  [ $d/100$  twice and  $s/10 + 18d/100$  once]

# Improved Solution for Sampling Woes

- ▶ Problem is that we are picking 1/10 of the queries
- ▶ We need to pick 1/10 of the users and pick all their queries
- ▶ If we can store 1/10 of the users, then for every query we can decide either to process or not
- ▶ **Improved Solution:** Hash user ID (actually, IP address) to 0 ... 9
  - ▣ Pick only those that hash to 0
- ▶ **Sampling Question:** How to sample at rate of 1/70?
- ▶ **Sampling Question:** How to sample at rate of 23/70?

# Sampling

- ▶ Sampling can be applied if the filtering test is easy (e.g., hash value = 0? Temperature > 22 degrees?)
- ▶ Sampling is harder if it involves a lookup (e.g., has this query been asked before by this user? Is this user among the top 10% of the frequent users list?)
- ▶ Other techniques are available for filtering
  - ▣ **Bloom Filters**

# Example: Bloom Filters for Spam

- ▶ **White lists:** allowed email addresses
  - ❑ Assume we have **1 Billion** allowed email addresses
  - ❑ Assume black list is much larger than white list
  - ❑ If each email address is 20 bytes, this takes 20 GB to store
- ▶ **Bloom Filters:** store white lists as bit hash arrays
  - ❑ Every email address is hashed and a 1 is stored in the location if it is in white list
  - ❑ In 1 GB, we can store hash array of size 8 Billion
- ▶ **Strict White Lists:** use bloom filters and then verify with real white list
- ▶ **Stricter White List:** use cascade of bloom filters

# Bloom Filters: Test for Membership

- ▶ Array of  $n$  bits, initially all 0's
- ▶ Collection of  $k$  hash functions. Each hash func maps a key to  $n$  buckets
- ▶ Given key  $K$ , compute  $K$  hash values and
  - ▣ Check that each location in bit array is a 1
  - ▣ Even if one is 0, then it fails the test

# False Positive Rate

- ▶ Assume we have  $x$  targets and  $y$  darts
- ▶ Prob a dart will hit a specific target =  $1/x$
- ▶ Prob a dart does not hit a specific target =  $1 - (1/x) = (x-1)/x$
- ▶ Prob that  $y$  darts miss a specific target =  $((x-1)/x)^y$
- ▶ Prob that  $y$  darts miss a specific target =  $e^{-y/x}$
- ▶ Let  $x = 8B$ ;  $y = 1B$ ; Then prob of missing a target =  $e^{-1/8}$
- ▶ Prob of hitting a target = false positive rate =  $1 - e^{-1/8} = 0.1175$
- ▶ If  $k = 2$ , the prob becomes  $(1 - e^{-1/4})^2 = 0.0493$

$$(1-h)^{1/h} = e^{-1} \text{ for small } h$$

# False Positive Rate

- ▶ Let  $n$  = bit array length = 8B
- ▶ Let  $m$  = # of members = 1B
- ▶ Let  $k$  = # of hash functions = 1
- ▶ Prob that a white list email hashes to a location =  $10^{-9}$
- ▶ False positive rate is given by

# Counting distinct elements

- ▶ How many unique users in a give period?
- ▶ How many users (IP addresses) visited a webpage?
  - ❑ Each IP address is 4 bytes = 32 bits
  - ❑ 4 billion IP addresses are possible = 16 GB
  - ❑ If we need this for each webpage and there are thousands, then we cannot store in memory

# Flajolet-Martin Algorithm

- ▶ For each element obtain a sufficiently long hash
  - ▣ Has to be more possible results of hash than elements in the universal set
  - ▣ Example, use 64 bits ( $2^{64} \sim 10^{19}$ ) to hash URLs (4 Billion)
  - ▣ High prob that different elements get different hash values
  - ▣ Some fraction of these hash values will be “unusual”
- ▶ We will focus on the ones that have  $r$  0s at the end of its hash value
  - ▣ Prob of hash value to end in  $r$  0s is  $2^{-r}$
  - ▣ Prob that  $m$  unique items have has values that don't end in  $r$  0s is  $(1-2^{-r})^m = e^{-m2^{-r}}$

# Summary

- ▶ Look at the probability =  $e^{-m2^{-r}}$
- ▶ If  $m$  is much larger than  $2^r$ , then prob approaches 1
- ▶ If  $m$  is much smaller than  $2^r$ , then prob approaches 0
- ▶ Thus  $2^R$  is a good choice, where  $R$  is the largest tail of 0s

# Clustering

# Clustering dogs using height & weight

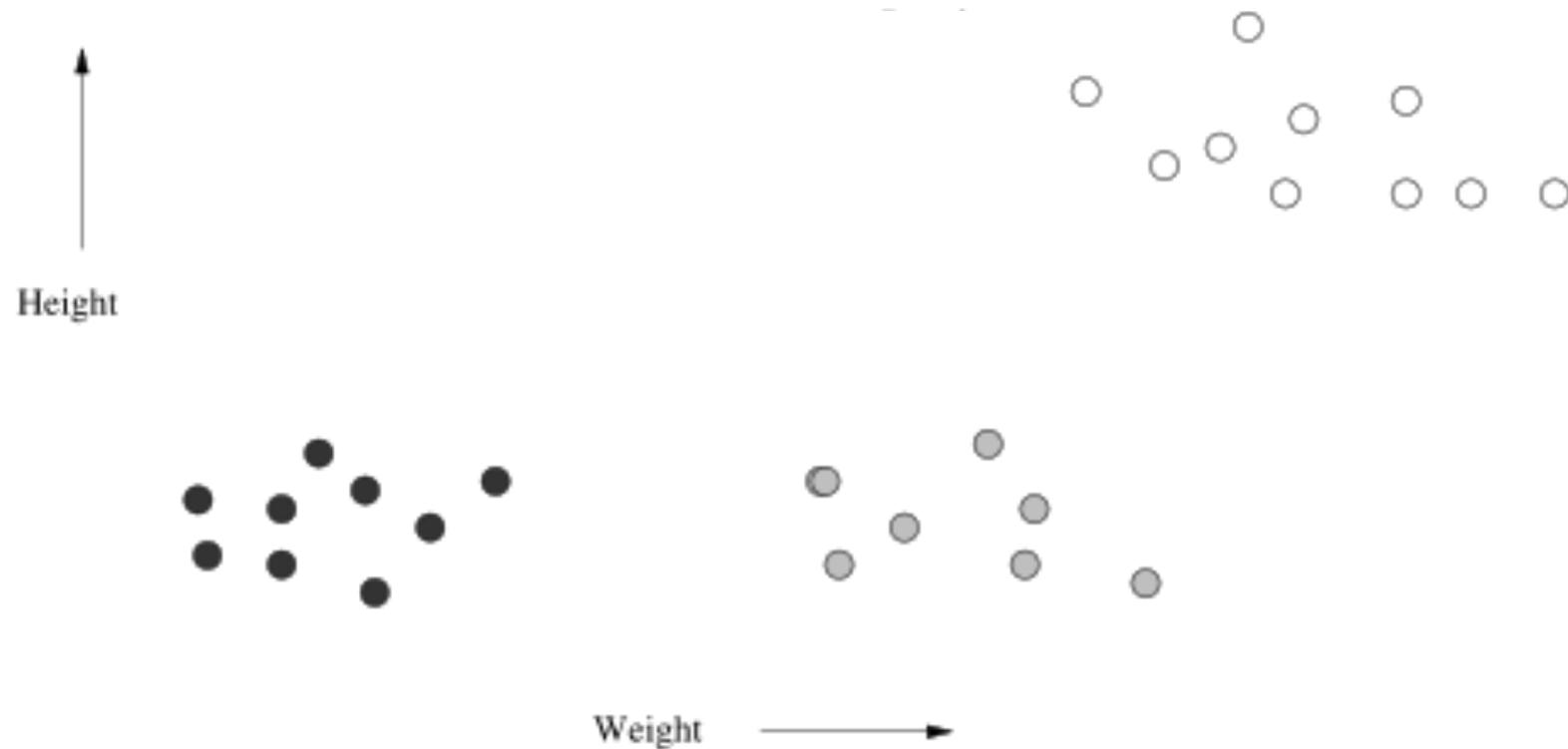


Figure 7.1: Heights and weights of dogs taken from three varieties

# Clustering dogs using height & weight

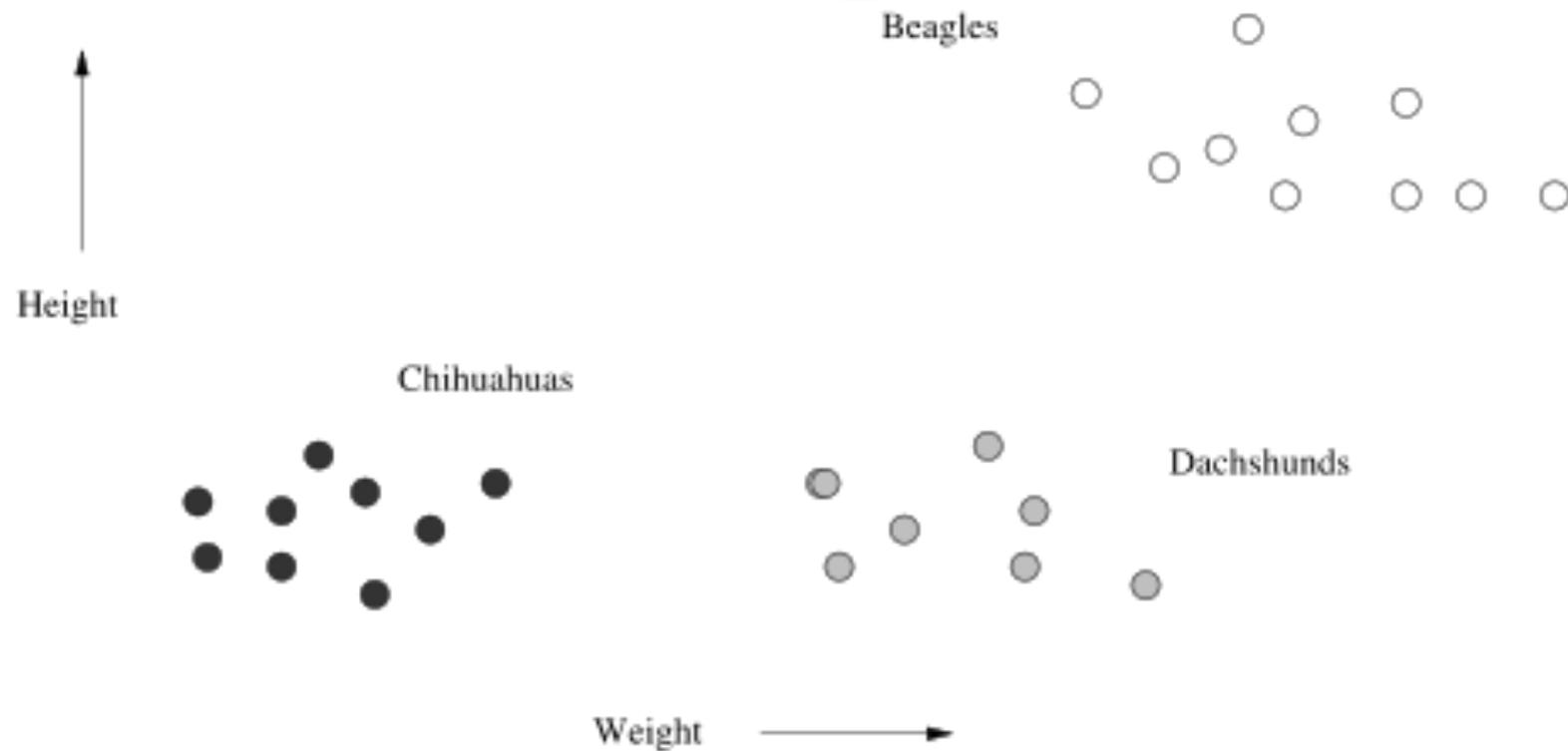


Figure 7.1: Heights and weights of dogs taken from three varieties

# Clustering

- ▶ Clustering is the process of making clusters, which put **similar** things together into same cluster ...
- ▶ And put **dissimilar** things into different clusters
- ▶ Need a similarity function
- ▶ Need a similarity **distance** function
  - ▣ Convenient to map items to points in space

# Distance Functions

- ▶ Jaccard Distance
  - ▶ Hamming Distance
  - ▶ Euclidean Distance
  - ▶ Cosine Distance
  - ▶ Edit Distance
  - ▶ ...
- ▶ What is a **distance** function
    - $D(x,y) \geq 0$
    - $D(x,y) = D(y,x)$
    - $D(x,y) \leq D(x,z) + D(z,y)$

# Clustering Strategies

- ▶ Hierarchical or Agglomerative
  - ▣ Bottom-up
- ▶ Partitioning methods
  - ▣ Top-down
- ▶ Density-based
- ▶ Cluster-based
- ▶ Iterative methods

# Curse of Dimensionality

- ▶ N points in d-dimensional space
  - If  $d = 1$ , then average distance =  $1/3$
  - As  $d$  gets larger, what is the average distance? Distribution of distances?
    - # of **nearby** points for any a given point **vanishes**. So, clustering does not work well
    - # of points at max distance ( $\sim\sqrt{d}$ ) also vanishes. Real range actually very small
  - Angle ABC given 3 points approaches 90
    - Denominator grows linearly with  $d$
    - Expected  $\cos = 0$  since equal points expected in all 4 quadrants

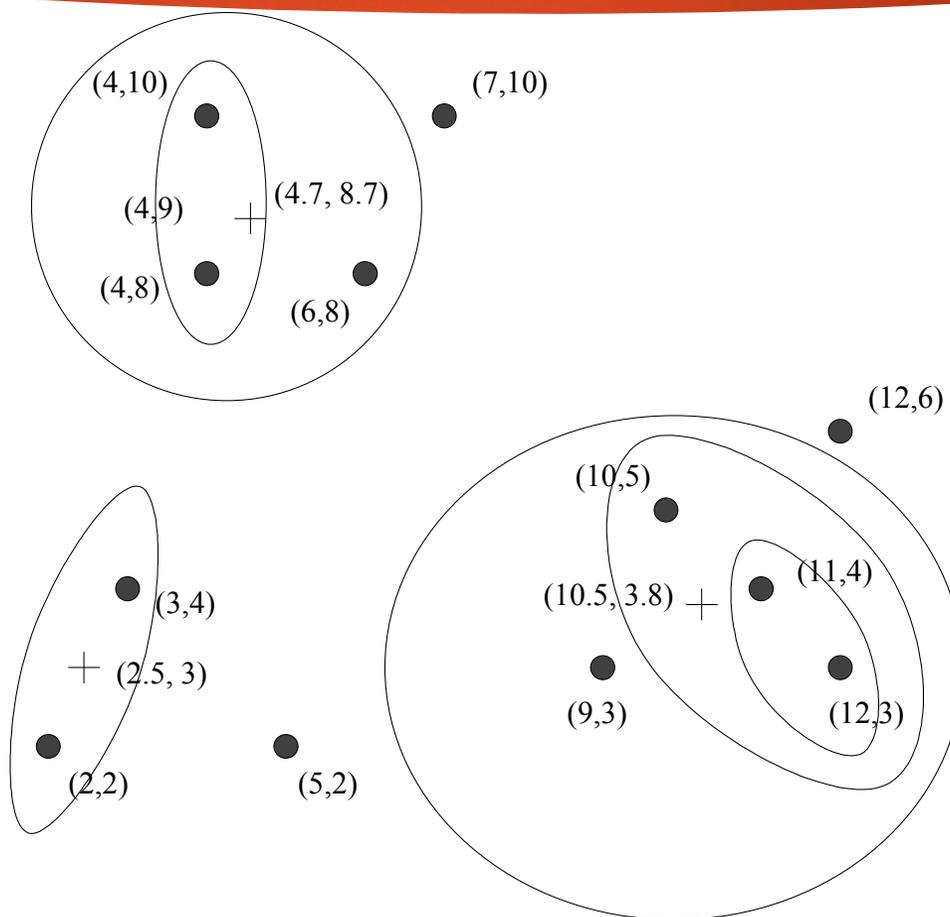
$$\frac{\sum_{i=1}^d x_i y_i}{\sqrt{\sum_{i=1}^d x_i^2} \sqrt{\sum_{i=1}^d y_i^2}}$$

# Hierarchical Clustering

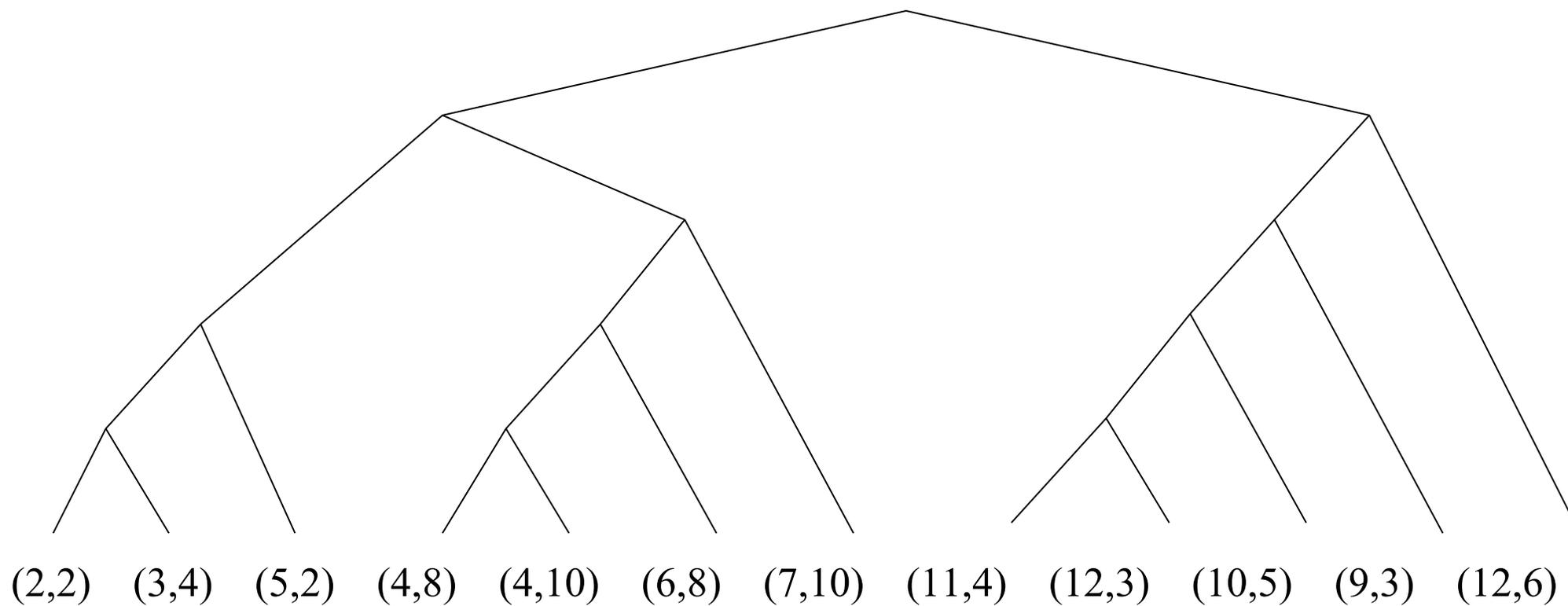
# Hierarchical Clustering

- ▶ Starts with each item in different clusters
- ▶ Bottom up
- ▶ In each iteration
  - ▣ Two clusters are identified and merged into one
- ▶ Items are combined as the algorithm progresses
- ▶ **Questions:**
  - ▣ How are clusters represented
  - ▣ How to decide which ones to merge
  - ▣ What is the stopping condition
- ▶ Typical algorithm: find smallest distance between nodes of different clusters

# Hierarchical Clustering



# Output of Clustering: Dendrogram



# Measures for a cluster

- ▶ Radius: largest distance from a centroid
- ▶ Diameter: largest distance between some pair of points in cluster
- ▶ Density: # of points per unit volume
- ▶ Volume: some power of radius or diameter
  
- ▶ **Good cluster**: when diameter of each cluster is much larger than its nearest cluster or nearest point outside cluster

# Stopping condition for clustering

- ▶ Cluster radius or diameter crosses a threshold
- ▶ Cluster density drops below a certain threshold
- ▶ Ratio of diameter to distance to nearest cluster drops below a certain threshold