Polynomial-time computations

- An algorithm has time complexity O(T(n)) if it runs in time at most cT(n) for <u>every</u> input of length n.
- An algorithm is a polynomial-time algorithm if its time complexity is O(p(n)), where p(n) is polynomial in n.

Polynomials

- If f(n) = polynomial function in n, then f(n) = O(n^c), for some fixed constant c
- If f(n) = exponential (super-polynomial) function in n,

then $f(n) = \omega(n^c)$, for any constant c

 Composition of polynomial functions are also polynomial, i.e.,

f(g(n)) = polynomial if f() and g() are polynomial

 If an algorithm calls another polynomial-time subroutine a polynomial number of times, then the time complexity is polynomial.



- A problem is in \mathcal{P} if there exists a polynomial-time algorithm that solves the problem.
- Examples of P
 - DFS: Linear-time algorithm exists
 - *Sorting:* O(n log n)-time algorithm exists
 - **Bubble Sort:** Quadratic-time algorithm O(n²)
 - APSP: Cubic-time algorithm O(n³)
- P is therefore a class of problems (not algorithms)!



- A problem is in *NP* if there exists a nondeterministic polynomial-time algorithm that solves the problem.
- A problem is in *P* if there exists a (deterministic) polynomial-time algorithm that verifies a solution to the problem.
- All problems in \mathcal{P} are in \mathcal{NP}

TSP: Traveling Salesperson Problem

- Input:
 - Weighted graph, G
 - Length bound, B
- Output:
 - Is there a traveling salesperson tour in G of length at most B?
- Is TSP in *MP*?
 - YES. Easy to verify a given solution.
- Is TSP in \mathcal{P} ?
 - OPEN!
 - One of the greatest unsolved problems of this century!
 - Same as asking: <u>Is P = MP?</u>

So, what is *MP*-Complete?

- *MP-Complete* problems are the "hardest" problems in *MP*.
- We need to formalize the notion of "hardest".

Terminology (Cont'd)

- Decision Problems:
 - Are problems for which the solution set is {yes, no}
 - Example: Does a given graph have an odd cycle?
 - Example: Does a given weighted graph have a TSP tour of length at most B?
- Complement of a decision problem:
 - Are problems for which the solution is "complemented".
 - Example: Does a given graph NOT have an odd cycle?
 - Example: Is every TSP tour of a given weighted graph of length greater than B?
- Optimization Problems:
 - Are problems where one is maximizing (or minimizing) some objective function.
 - Example: Given a weighted graph, find a MST.
 - Example: Given a weighted graph, find an optimal TSP tour.
- Verification Algorithms:
 - Given a problem instance i and a certificate s, is s a solution for instance i?

Terminology (Cont'd)

- Complexity Class P :
 - Set of all problems *p* for which polynomial-time algorithms exist.
- Complexity Class *MP* :
 - Set of all problems *p* for which polynomial-time verification algorithms exist.
- Complexity Class co-MP :
 - Set of all problems p for which polynomial-time verification algorithms exist for their complements, I.e., their complements are in *TP*.

Terminology (Cont'd)

- Reductions: $p_1 \rightarrow p_2$
 - A problem p_1 is reducible to p_2 , if there exists an algorithm R that takes an instance i_1 of p_1 and outputs an instance i_2 of p_2 , with the constraint that the solution for i_1 is YES if and only if the solution for i_2 is YES.
 - Thus, R converts YES (NO) instances of p₁ to YES (NO) instances of p₂.
- Polynomial-time reductions: $p_1 \xrightarrow{p} p_2$
 - Reductions that run in polynomial time.

• If
$$p_1 \xrightarrow{p} p_2$$
, then
-If p_2 is easy, then so is p_1 .
-If p_1 is hard, then so is p_2 .

$$\mathbf{p}_2 \in \boldsymbol{\mathcal{P}} \Rightarrow \mathbf{p}_1 \in \boldsymbol{\mathcal{P}}$$

$$\mathbf{p}_1 \notin \boldsymbol{\mathcal{P}} \Rightarrow \mathbf{p}_2 \notin \boldsymbol{\mathcal{P}}$$

The problem classes and their relationships

