

# COT 6405: Analysis of Algorithms

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[www.cs.fiu.edu/~giri/teach/6405F19.html](http://www.cs.fiu.edu/~giri/teach/6405F19.html)

# Sorting Algorithms

- SelectionSort
- InsertionSort
- BubbleSort
- ShakerSort
- MergeSort
- HeapSort
- QuickSort
- Bucket & Radix Sort
- Counting Sort

# Solving Recurrence Relations

Recurrence; Cond	Solution
$T(n) = T(n-1) + O(1)$	$T(n) = O(n)$
$T(n) = T(n-1) + O(n)$	$T(n) = O(n^2)$
$T(n) = T(n-c) + O(1)$	$T(n) = O(n)$
$T(n) = T(n-c) + O(n)$	$T(n) = O(n^2)$
$T(n) = 2T(n/2) + O(n)$	$T(n) = O(n \log n)$
$T(n) = aT(n/b) + O(n);$ $a = b$	$T(n) = O(n \log n)$
$T(n) = aT(n/b) + O(n);$ $a < b$	$T(n) = O(n)$
$T(n) = aT(n/b) + f(n);$ $f(n) = O(n^{\log_b a - \epsilon})$	$T(n) = O(n)$
$T(n) = aT(n/b) + f(n);$ $f(n) = O(n^{\log_b a})$	$T(n) = \Theta(n^{\log_b a} \log n)$
$T(n) = aT(n/b) + f(n);$ $f(n) = \Theta(f(n))$ $af(n/b) \leq cf(n)$	$T(n) = \Omega(n^{\log_b a} \log n)$

# Solving Recurrences: Recursion-tree method

- Substitution method fails when a good guess is not available
- Recursion-tree method works in those cases
  - Write down the recurrence as a tree with recursive calls as the children
  - Expand the children
  - Add up each level
  - Sum up the levels
- Useful for analyzing divide-and-conquer algorithms
- Also useful for generating good guesses to be used by substitution method

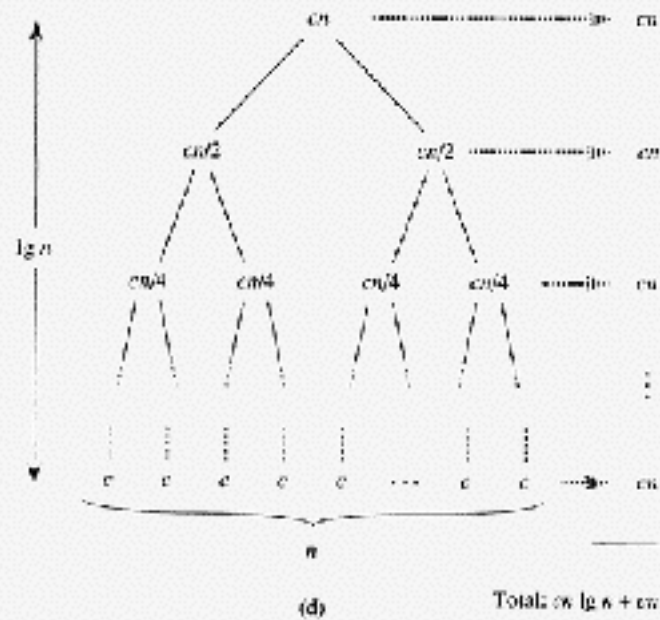
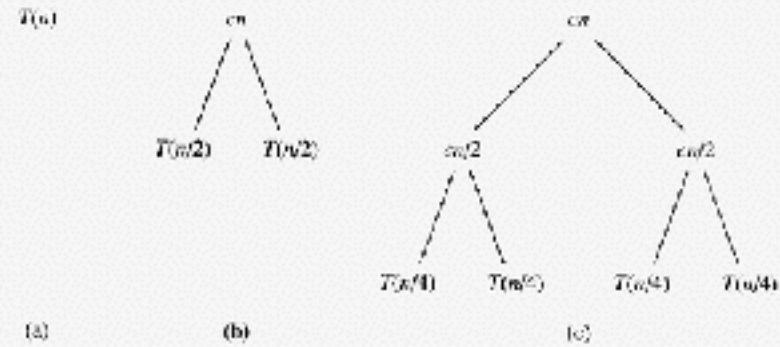
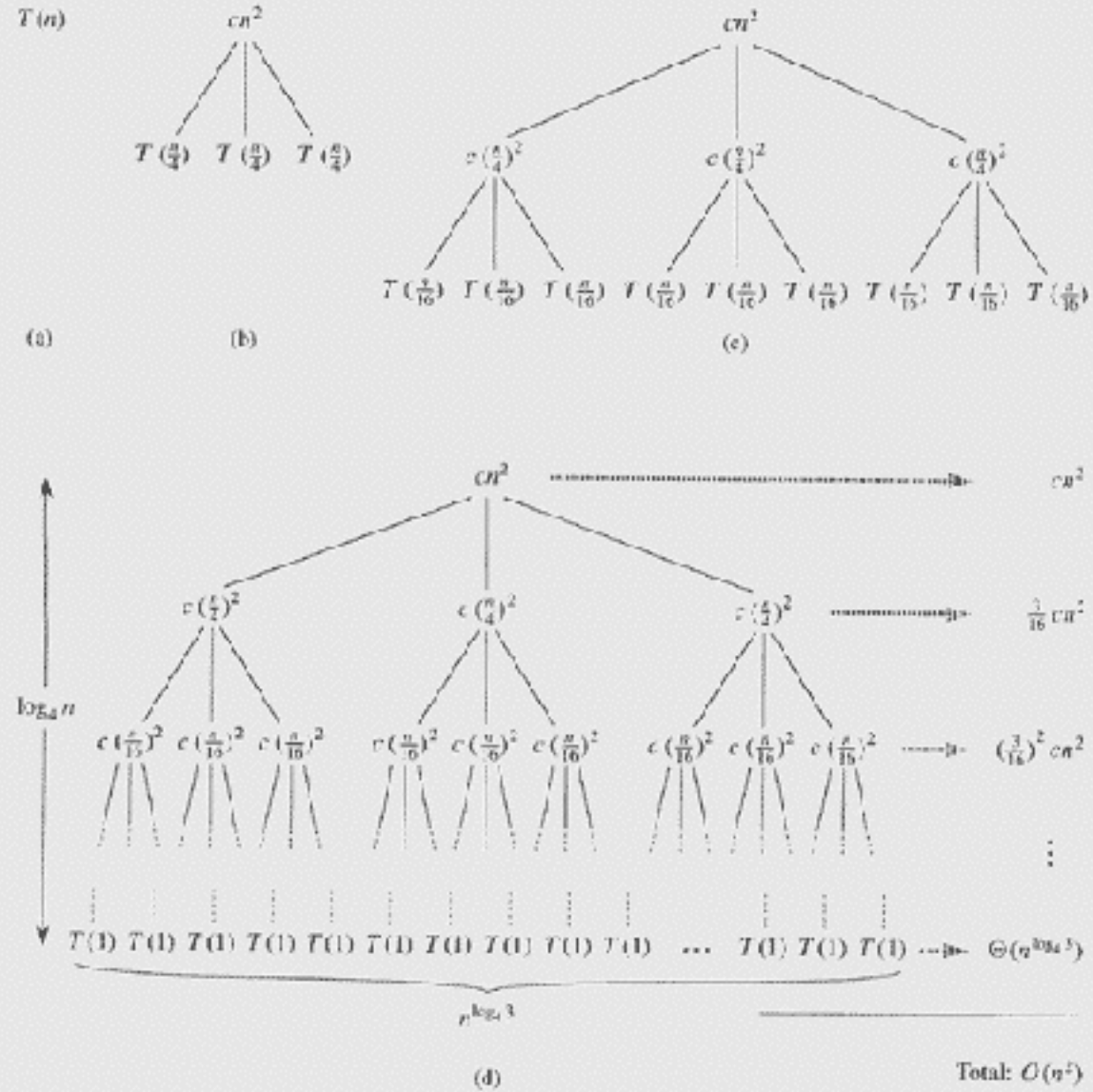
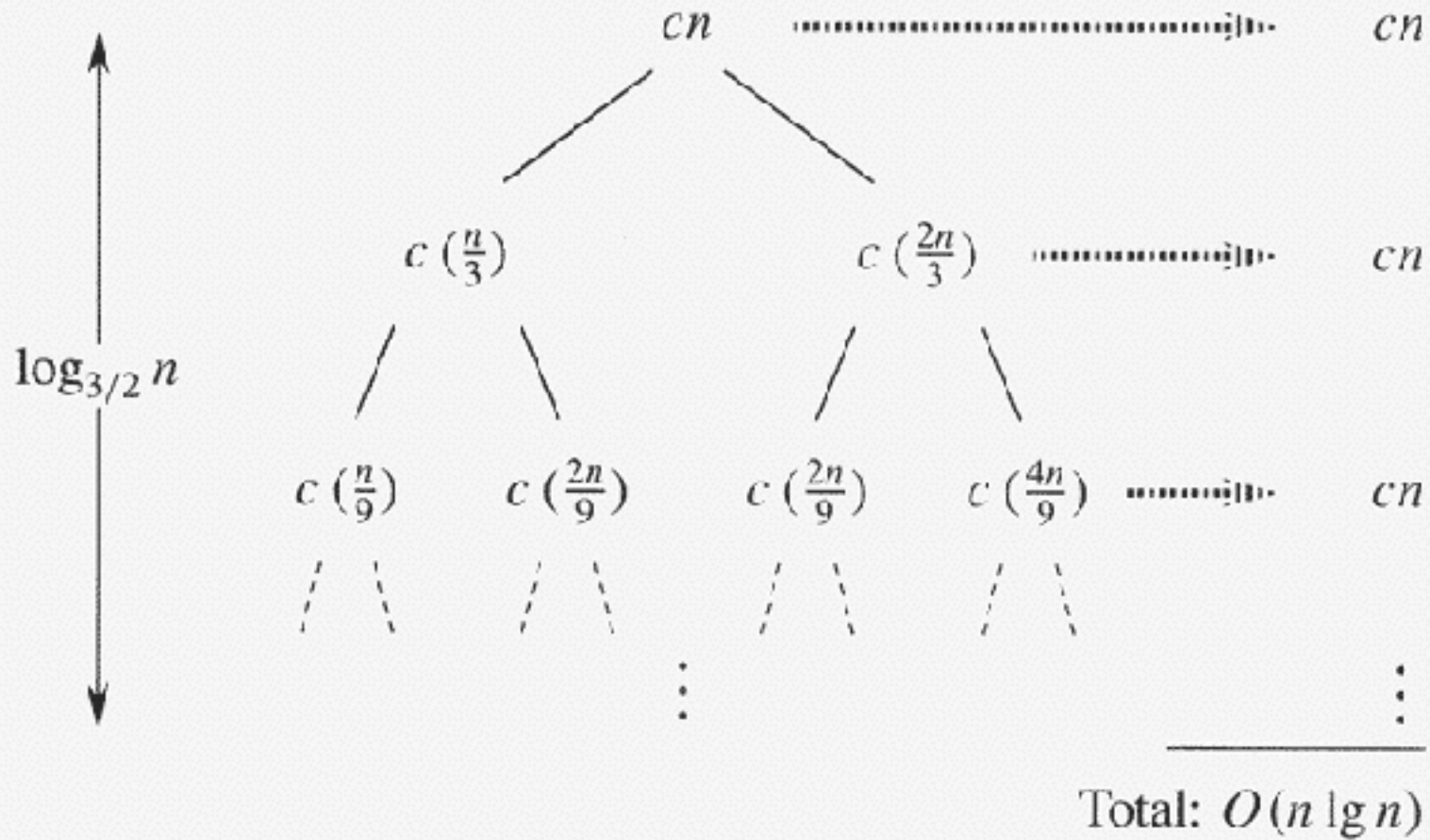


Figure 2.5 The construction of a recursion tree for the recurrence  $T(n) = 2T(n/2) + cn$ . Part (a) shows  $T(n)$ , which is progressively expanded in (b)–(d) to form the recursion tree. The fully expanded tree in part (d) has  $\lg n + 1$  levels (i.e., it has height  $\lg n$ , as indicated), and each level contributes a total cost of  $cn$ . The total cost, therefore, is  $cn \lg n + cn$ , which is  $\Theta(n \lg n)$ .



**Figure 4.1** The construction of a recursion tree for the recurrence  $T(n) = 3T(n/4) + cn^2$ . Part (a) shows  $T(n)$ , which is progressively expanded in (b)–(d) to form the recursion tree. The fully expanded tree in part (d) has height  $\log_4 n$  (it has  $\log_4 n + 1$  levels).



**Figure 4.2** A recursion tree for the recurrence  $T(n) = T(n/3) + T(2n/3) + cn$ .

# Solving Recurrences using Master Theorem

## Master Theorem:

Let  $a, b \geq 1$  be constants, let  $f(n)$  be a function, and let

$$T(n) = aT(n/b) + f(n)$$

1. If  $f(n) = O(n^{\log_b a - \epsilon})$  for some constant  $\epsilon > 0$ , then
  - ▶  $T(n) = \Theta(n^{\log_b a})$
2. If  $f(n) = \Theta(n^{\log_b a})$ , then
  - ▶  $T(n) = \Theta(n^{\log_b a} \log n)$
3. If  $f(n) = \Omega(n^{\log_b a + \epsilon})$  for some constant  $\epsilon > 0$ , then
  - ▶  $T(n) = \Theta(f(n))$



# QuickSort

Page 146, CLR

```
QuickSort(A, p, r)
```

```
  if (p < r) then
```

```
    q = Partition(A, p, r)
```

```
    QuickSort(A, p, q-1)
```

```
    QuickSort(A, q+1, r)
```

```
Partition(A, p, r)
```

```
  x = A[r]
```

```
  i = p-1
```

```
  for j = p to r-1 do
```

```
    if A[j] <= x then
```

```
      i++
```

```
      exchange(A[i], A[j])
```

```
  exchange(A[i+1], A[r])
```

```
  return i+1
```

# HeapSort Analysis

For the HeapSort analysis, we need to compute:

$$\sum_{h=0}^{\lfloor \log n \rfloor} \frac{h}{2^h}$$

We know from the formula for geometric series that

$$\sum_{k=0}^{\infty} x^k = \frac{1}{1-x}$$

Differentiating both sides, we get

$$\sum_{k=0}^{\infty} kx^{k-1} = \frac{1}{(1-x)^2}$$

Multiplying both sides by  $x$  we get

$$\sum_{k=0}^{\infty} kx^k = \frac{x}{(1-x)^2}$$

Now replace  $x = 1/2$  to show that

$$\sum_{h=0}^{\lfloor \log n \rfloor} \frac{h}{2^h} \leq \frac{1}{2}$$

# SelectionSort – Worst-case analysis

```
SELECTIONSORT(array A)
1   $N \leftarrow \text{length}[A]$ 
2  for  $p \leftarrow 1$  to  $N$ 
    do  $\triangleright$  Compute  $j$ 
3       $j \leftarrow p$ 
4      for  $m \leftarrow p + 1$  to  $N$ 
5          do if  $(A[m] < A[j])$ 
6              then  $j \leftarrow m$ 
7           $\triangleright$  Swap  $A[p]$  and  $A[j]$ 
8           $\text{temp} \leftarrow A[p]$ 
9           $A[p] \leftarrow A[j]$ 
           $A[j] \leftarrow \text{temp}$ 
```

N-p comparisons

3 data movements

# Invariant for SelectionSort

- An appropriate invariant has a parameter related to the progress of the algorithm (e.g., iteration number)
- An appropriate invariant helps in proving algorithm is correct
- **“At the end of iteration  $p$ , the  $p$  smallest items are in their correct location”**

# Algorithm Invariants

- **Selection Sort**
  - iteration  $k$ : the  $k$  smallest items are in correct location.
- **Insertion Sort**
  - iteration  $k$ : the first  $k$  items are in sorted order.
- **Bubble Sort**
  - In each pass, every item that does not have a smaller item after it, is moved as far up in the list as possible.
  - Iteration  $k$ :  $k$  smallest items are in the correct location.
- **Shaker Sort**
  - In each odd (even) numbered pass, every item that does not have a smaller (larger) item after it, is moved as far up (down) in the list as possible.
  - Iteration  $k$ : the  $k/2$  smallest and largest items are in the correct location.

# Algorithm Invariants (Cont'd)

- **Merge (many lists)**
  - Iteration  $k$ : the  $k$  smallest items from the lists are merged.
- **Heapify**
  - Iteration with  $i = k$ : Subtrees with roots at indices  $k$  or larger satisfy the heap property.
- **HeapSort**
  - Iteration  $k$ : Largest  $k$  items are in the right location.
- **Partition (two sublists)**
  - Iteration  $k$  (with pointers at  $i$  and  $j$ ): items in locations  $[1..i]$  (locations  $[i+1..j]$ ) are at least as small (large) as the pivot.

# Definition of big-Oh

➤ We say that

➤  $F(n) = O(G(n))$

If there exists two positive constants,  $c$  and  $n_0$ , such that

➤ For all  $n \geq n_0$ , we have  $F(n) \leq c G(n)$

- Thus, to show that  $F(n) = O(G(n))$ , you need to find two positive constants that satisfy the condition mentioned above
- Also, to show that  $F(n) \neq O(G(n))$ , you need to show that for any value of  $c$ , there does not exist a positive constant  $n_0$  that satisfies the condition mentioned above

# Algorithm Analysis

- **Worst-case time complexity\***
  - Worst possible time of all input instances of length  $N$
- **(Worst-case) space complexity**
  - Worst possible space of all input instances of length  $N$
- **Average-case time complexity**
  - Average time of all input instances of length  $N$



# Computation Tree for A on n inputs

- Assume A is a comparison-based sorting alg
- Every node represents a comparison between two items in A
- Branching based on result of comparison
- Leaf corresponds to algorithm halting with output
- Every input follows a path in tree
- Different inputs follow different paths
- Time complexity on input  $x$  = depth of leaf where it ends on input  $x$

# Upper and Lower Bounds

## ➤ Time Complexity of a Problem

- **Difficulty:** Since there can be many algorithms that solve a problem, what time complexity should we pick?
- **Solution:** Define upper bounds and lower bounds within which the time complexity lies.

## ➤ What is the **upper** bound on time complexity of sorting?

- **Answer:** Since SelectionSort runs in worst-case  $O(N^2)$  and MergeSort runs in  $O(N \log N)$ , either one works as an upper bound.
- **Critical Point:** Among all upper bounds, the best is the lowest possible upper bound, i.e., time complexity of the best algorithm.

## ➤ What is the **lower** bound on time complexity of sorting?

- **Difficulty:** If we claim that lower bound is  $O(f(N))$ , then we have to prove that no algorithm that sorts  $N$  items can run in worst-case time  $o(f(N))$ .

# Lower Bounds

- It's possible to prove lower bounds for many comparison-based problems.
- For comparison-based problems, for inputs of length  $N$ , if there are  $P(N)$  possible solutions, then
  - any algorithm needs  $\log_2(P(N))$  to solve the problem.
- Binary Search on a list of  $N$  items has at least  $N + 1$  possible solutions. Hence lower bound is
  - $\log_2(N+1)$ .
- Sorting a list of  $N$  items has at least  $N!$  possible solutions. Hence lower bound is
  - $\log_2(N!) = O(N \log N)$
- Thus, **MergeSort is an optimal algorithm.**
  - Because its worst-case time complexity equals lower bound!

# Beating the Lower Bound

## ➤ Bucket Sort

- Runs in time  $O(N+K)$  given  $N$  integers in range  $[a+1, a+K]$
- If  $K = O(N)$ , we are able to sort in  $O(N)$
- How is it possible to beat the lower bound?
- Only because we know more about the data.
- If nothing is known about the data, the lower bound holds.

## ➤ Radix Sort

- Runs in time  $O(d(N+K))$  given  $N$  items with  $d$  digits each in range  $[1, K]$

## ➤ Counting Sort

- Runs in time  $O(N+K)$  given  $N$  items in range  $[a+1, a+K]$

# Stable Sort

- A sort is **stable** if equal elements appear in the same order in both the input and the output.
- Which sorts are stable? Homework!

# Order Statistics

## ➤ Maximum, Minimum

### ➤ Upper Bound

- $O(n)$  because ??
- We have an algorithm with a single for-loop:  $n-1$  comparisons

### ➤ Lower Bound

- $n-1$  comparisons

## ➤ MinMax

- Upper Bound:  $2(n-1)$  comparisons
- Lower Bound:  $3n/2$  comparisons

## ➤ Max and 2ndMax

- Upper Bound:  $(n-1) + (n-2)$  comparisons
- Lower Bound: **Harder to prove**

7	3	1	9	4	8	2	5
---	---	---	---	---	---	---	---

$\text{Rank}_A(x) =$   
position of  $x$  in  
sorted order of

# k-Selection; Median

- Select the **k**-th smallest item in list
- Naïve Solution
  - Sort;
  - pick the **k**-th smallest item in sorted list.  
 **$O(n \log n)$**  time complexity
- Idea: Modify Partition from QuickSort
  - How?
- Randomized solution: Average case  **$O(n)$**
- Improved Solution: worst case  **$O(n)$**

# Using Partition for k-Selection

```
PARTITION(array A, int p, int r)
1  x ← A[r]           ▷ Choose pivot
2  i ← p - 1
3  for j ← p to r - 1
4      do if (A[j] ≤ x)
5          then i ← i + 1
6              exchange A[i] ↔ A[j]
7  exchange A[i + 1] ↔ A[r]
8  return i + 1
```

- Perform Partition from QuickSort (assume all unique items)
- Rank(pivot) = 1 + # of items that are smaller than pivot
- If Rank(pivot) = k, we are done
- Else, recursively perform k-Selection in one of the two partitions



# QuickSelect: a variant of QuickSort

QUICKSELECT(*array A, int k, int p, int r*)

▷ Select  $k$ -th largest in subarray  $A[p..r]$

1 **if** ( $p = r$ )

2     **then return**  $A[p]$

3  $q \leftarrow$  PARTITION( $A, p, r$ )

4  $i \leftarrow q - p + 1$      ▷ Compute rank of pivot

5 **if** ( $i = k$ )

6     **then return**  $A[q]$

7 **if** ( $i > k$ )

8     **then return** QUICKSELECT( $A, k, p, q$ )

9     **else** **return** QUICKSELECT( $A, k - i, q + 1, r$ )

# k-Selection Time Complexity

- Perform Partition from QuickSort (assume all unique items)
- Rank(pivot) = 1 + # of items that are smaller than **pivot**
- If Rank(pivot) = k, we are done
- Else, recursively perform k-Selection in one of the two partitions

- On the average:
  - Rank(pivot) =  $n / 2$
- Average-case time
  - $T(N) = T(N/2) + O(N)$
  - $T(N) = O(N)$
- Worst-case time
  - $T(N) = T(N-1) + O(N)$
  - $T(N) = O(N^2)$

```

PARTITION(array A, int p, int r)
1  x ← A[r]                                ▷ Choose pivot
2  i ← p - 1
3  for j ← p to r - 1
4      do if (A[j] ≤ x)
5          then i ← i + 1
6              exchange A[i] ↔ A[j]
7  exchange A[i + 1] ↔ A[r]
8  return i + 1
  
```

# Randomized Solution for k-Selection

- Uses RandomizedPartition instead of Partition
  - RandomizedPartition picks the pivot uniformly at random from among the elements in the list to be partitioned.
- Randomized k-Selection runs in  $O(N)$  time on the average
- Worst-case behavior is very poor  $O(N^2)$

# Readings for next class

- **Trees,**
- **Binary Trees,**
- **Binary Search Trees,**
- **Balanced Binary Search Trees**