Polynomial-time computations

- An algorithm has time complexity O(T(n)) if it runs in time at most cT(n) for <u>every</u> input of length n.
- An algorithm is a polynomial-time algorithm if its time complexity is O(p(n)), where p(n) is polynomial in n.

Polynomials

- If f(n) = polynomial function in n, then f(n) = O(n^c), for some fixed constant c
- If f(n) = exponential (super-polynomial) function in n,

then $f(n) = \omega(n^c)$, for any constant c

 Composition of polynomial functions are also polynomial, i.e.,

f(g(n)) = polynomial if f() and g() are polynomial

 If an algorithm calls another polynomial-time subroutine a polynomial number of times, then the time complexity is polynomial.

The class **P**

- A problem is in \mathcal{P} if there exists a polynomial-time algorithm that solves the problem.
- Examples of P
 - DFS: Linear-time algorithm exists
 - *Sorting:* O(n log n)-time algorithm exists
 - **Bubble Sort:** Quadratic-time algorithm O(n²)
 - APSP: Cubic-time algorithm O(n³)
- P is therefore a class of problems (not algorithms)!



- A problem is in *NP* if there exists a nondeterministic polynomial-time algorithm that solves the problem.
- A problem is in *P* if there exists a (deterministic) polynomial-time algorithm that verifies a solution to the problem.
- All problems in \mathcal{P} are in \mathcal{NP}

TSP: Traveling Salesperson Problem

- Input:
 - Weighted graph, G
 - Length bound, B
- Output:
 - Is there a traveling salesperson tour in G of length at most B?
- Is TSP in *MP*?
 - YES. Easy to verify a given solution.
- Is TSP in \mathcal{P} ?
 - OPEN!
 - One of the greatest unsolved problems of this century!
 - Same as asking: <u>Is P = MP?</u>

So, what is *MP*-Complete?

- *MP-Complete* problems are the "hardest" problems in *MP*.
- We need to formalize the notion of "hardest".

Terminology

- Problem:
 - An <u>abstract problem</u> is a function (relation) from a set I of instances of the problem to a set S of solutions.

 $p: I \rightarrow S$

- An <u>instance</u> of a problem *p* is obtained by assigning values to the parameters of the abstract problem.
- Thus, describing the set of all instances (I.e., possible inputs) and the set of corresponding outputs defines a problem.
- Algorithm:
 - An algorithm that solves problem *p* must give correct solutions to all instances of the problem.
- Polynomial-time algorithm:

- Input Length:
 - length of an <u>encoding</u> of an instance of the problem.
 - Time and space complexities are written in terms of it.
- Worst-case time/space complexity of an algorithm
 - Is the maximum time/space required by the algorithm on any input of length n.
- Worst-case time/space complexity of a problem
 - UPPER BOUND: worst-case time complexity of best existing algorithm that solves the problem.
 - LOWER BOUND: (provable) worst-case time complexity of best algorithm (need not exist) that could solve the problem.
 - LOWER BOUND \leq UPPER BOUND
- Complexity Class P:
 - Set of all problems *p* for which polynomial-time algorithms exist

- Decision Problems:
 - Are problems for which the solution set is {yes, no}
 - Example: Does a given graph have an odd cycle?
 - Example: Does a given weighted graph have a TSP tour of length at most B?
- Complement of a decision problem:
 - Are problems for which the solution is "complemented".
 - Example: Does a given graph NOT have an odd cycle?
 - Example: Is every TSP tour of a given weighted graph of length greater than B?
- Optimization Problems:
 - Are problems where one is maximizing (or minimizing) some objective function.
 - Example: Given a weighted graph, find a MST.
 - Example: Given a weighted graph, find an optimal TSP tour.
- Verification Algorithms:
 - Given a problem instance i and a certificate s, is s a solution for instance i?

- Complexity Class P :
 - Set of all problems *p* for which polynomial-time algorithms exist.
- Complexity Class *MP* :
 - Set of all problems *p* for which polynomial-time verification algorithms exist.
- Complexity Class co-MP :
 - Set of all problems p for which polynomial-time verification algorithms exist for their complements, I.e., their complements are in *TP*.

- Reductions: $p_1 \rightarrow p_2$
 - A problem p_1 is reducible to p_2 , if there exists an algorithm R that takes an instance i_1 of p_1 and outputs an instance i_2 of p_2 , with the constraint that the solution for i_1 is YES if and only if the solution for i_2 is YES.
 - Thus, R converts YES (NO) instances of p₁ to YES (NO) instances of p₂.
- Polynomial-time reductions: $p_1 \xrightarrow{p} p_2$
 - Reductions that run in polynomial time.

• If
$$p_1 \xrightarrow{p} p_2$$
, then
-If p_2 is easy, then so is p_1 .
-If p_1 is hard, then so is p_2 .

$$\mathbf{p}_2 \in \boldsymbol{\mathcal{P}} \Rightarrow \mathbf{p}_1 \in \boldsymbol{\mathcal{P}}$$

$$\mathbf{p}_1 \notin \mathbf{\mathcal{P}} \Rightarrow \mathbf{p}_2 \notin \mathbf{\mathcal{P}}$$

What are *MP*-Complete problems?

- These are the hardest problems in \mathcal{WP} .
- A problem p is *MP-Complete* if
 - there is a polynomial-time reduction from <u>every</u> problem in *VP* to p.
 - $p \in \mathcal{HP}$
- How to prove that a problem is *MP Complete*?

Cook's Theorem: [1972]

-The <u>SAT</u> problem is *MP*-Complete.

Steve Cook, Richard Karp, Leonid Levin

NP-Complete vs NP-Hard

- A problem p is *NP*-Complete if
 - there is a polynomial-time reduction from <u>every</u> problem in *NP* to p.
 - $p \in \mathcal{HP}$
- A problem p is *MP-Hard* if
 - there is a polynomial-time reduction from <u>every</u> problem in *NP* to p.

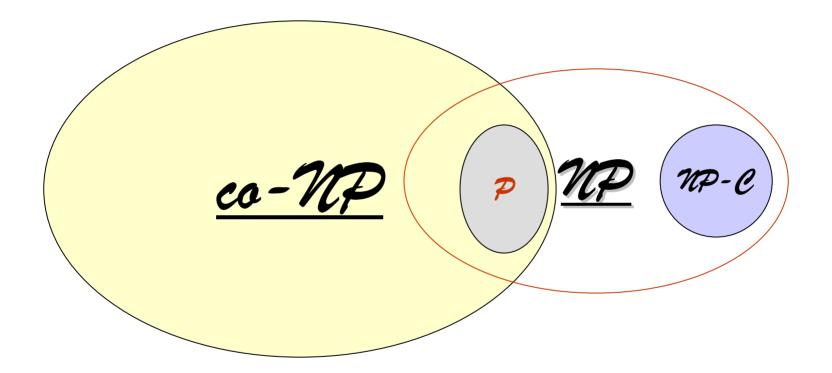
The SAT Problem: an example

- Consider the boolean expression: $C = (a \lor \neg b \lor c) \land (\neg a \lor d \lor \neg e) \land (a \lor \neg d \lor \neg c)$
- Is C satisfiable?
- Does there exist a True/False assignments to the boolean variables a, b, c, d, e, such that C is True?
- Set a = True and d = True. The others can be set arbitrarily, and C will be true.
- If C has 40,000 variables and 4 million clauses, then it becomes hard to test this.
- If there are n boolean variables, then there are 2ⁿ different truth value assignments.
- However, a solution can be quickly verified!

The SAT (Satisfiability) Problem

- Input: Boolean expression C in Conjunctive normal form (CNF) in n variables and m clauses.
- Question: Is C satisfiable?
 - Let $C = C_1 \wedge C_2 \wedge \dots \wedge C_m$
 - Where each $C_i = (y_1^i \lor y_2^i \lor \cdots \lor y_{k_i}^i)$
 - And each $\mathcal{Y}_{j}^{i} \in \{\mathbf{x}_{1}, \neg, \mathbf{x}_{1}, \mathbf{x}_{2}, \neg, \mathbf{x}_{2}, ..., \mathbf{x}_{n}, \neg, \mathbf{x}_{n}\}$
 - We want to know if there exists a truth assignment to all the variables in the boolean expression C that makes it true.
- Steve Cook showed that the problem of deciding whether a non-deterministic Turing machine T accepts an input w or not can be written as a boolean expression C_T for a SAT problem. The boolean expression will have length bounded by a polynomial in the size of T and w.
- How to now prove Cook's theorem? Is SAT in *MP*?
- Can every problem in \mathcal{TP} be poly. reduced to it ?

The problem classes and their relationships



More *MP*-*Complete* problems

<u>35AT</u>

- Input: Boolean expression C in Conjunctive normal form (CNF) in n variables and m clauses. Each clause has at most <u>three</u> literals.
- Question: Is C satisfiable?
 - Let $C = C_1 \wedge C_2 \wedge \dots \wedge C_m$
 - Where each $C_i = (y_1^i \lor y_2^i \lor y_3^i)$
 - And each $\mathcal{Y}_{j}^{i} \in \{\mathbf{x}_{1}, \neg, \mathbf{x}_{1}, \mathbf{x}_{2}, \neg, \mathbf{x}_{2}, ..., \mathbf{x}_{n}, \neg, \mathbf{x}_{n}\}$
 - We want to know if there exists a truth assignment to all the variables in the boolean expression C that makes it true.

3SAT is MP-Complete.

More *MP*-*Complete* problems?

<u>25AT</u>

- Input: Boolean expression C in Conjunctive normal form (CNF) in n variables and m clauses. Each clause has at most <u>three</u> literals.
- Question: Is C satisfiable?
 - Let $C = C_1 \wedge C_2 \wedge \dots \wedge C_m$
 - Where each $C_i = (y_1^i \lor y_2^i)$
 - And each $\mathcal{Y}_{j}^{i} \in \{\mathbf{x}_{1}, \neg, \mathbf{x}_{1}, \mathbf{x}_{2}, \neg, \mathbf{x}_{2}, ..., \mathbf{x}_{n}, \neg, \mathbf{x}_{n}\}$
 - We want to know if there exists a truth assignment to all the variables in the boolean expression C that makes it true.

2SAT is in \mathcal{P} .

3SAT is MP-Complete

- 35AT is in *MP*.
- SAT can be reduced in polynomial time to 3SAT.
- This implies that every problem in *m* can be reduced in polynomial time to 3SAT. Therefore, 3SAT is *m*-*Complete*.
- So, we have to design an algorithm such that:
- Input: an instance C of SAT
- Output: an instance C' of 3SAT such that satisfiability is retained. In other words, C is satisfiable if and only if C' is satisfiable.

3SAT is MP-Complete

- Let C be an instance of SAT with clauses $C_1, C_2, ..., C_m$
- Let C_i be a disjunction of k > 3 literals. $C_i = y_1 \lor y_2 \lor ... \lor y_k$
- Rewrite C_i as follows:

$$\mathbf{z}_{i} = (\mathbf{y}_{1} \lor \mathbf{y}_{2} \lor \mathbf{z}_{1}) \land \\ (\neg \mathbf{z}_{1} \lor \mathbf{y}_{3} \lor \mathbf{z}_{2}) \land \\ (\neg \mathbf{z}_{2} \lor \mathbf{y}_{4} \lor \mathbf{z}_{3}) \land$$

$$(\neg \mathbf{z}_{k-3} \lor \mathbf{y}_{k-1} \lor \mathbf{y}_k)$$

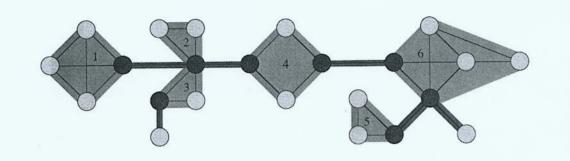
• Claim: C_i is satisfiable if and only if C'_i is satisfiable.

2SAT is in P

- If there is only one literal in a clause, it must be set to true.
- If there are two literals in some clause, and if one of them is set to false, then the other must be set to true.
- Using these constraints, it is possible to check if there is some inconsistency.
- How? Homework problem!

The CLIQUE Problem

• A clique is a completely connected subgraph.

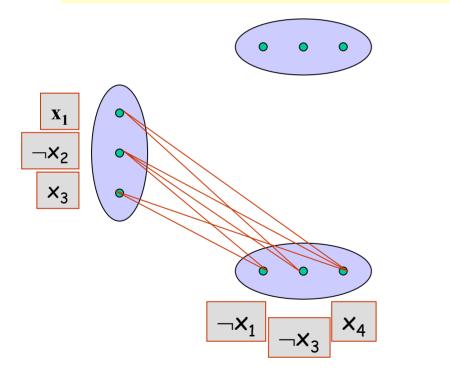


<u>CLIQUE</u>

- Input: Graph G(V,E) and integer k
- Question: Does G have a clique of size k?

CLIQUE is NP-Complete

- CLIQUE is in *MP*.
- · Reduce 3SAT to CLIQUE in polynomial time.
- $F = (x_1 \lor \neg x_2 \lor x_3) (\neg x_1 \lor \neg x_3 \lor x_4) (x_2 \lor x_3 \lor \neg x_4) (\neg x_1 \lor \neg x_2 \lor x_3)$



F is satisfiable if and only if G has a clique of size k where k is the number of clauses in F.

0

 \bigcirc