Augmented Data Structures

• Why is it needed?
  - Because basic data structures not enough for all operations
  - storing extra information helps execute special operations more efficiently.

• Can any data structure be augmented?
  - Yes. Any data structure can be augmented.

• Can a data structure be augmented with any additional information?
  - Theoretically, yes.

• How to choose which additional information to store.
  - Only if we can maintain the additional information efficiently under all operations. That means, with additional information, we need to perform old and new operations efficiently maintain the additional information efficiently.
New Operations on RB-Trees

- Basic operations
  - RB-Search, RB-Insert, RB-Delete

- New Operations
  - Rank(T,x)
  - Select(T,k)
  - NO EFFICIENT WAY TO IMPLEMENT THEM!
  - Unless more information is stored in each node!

- What information to be added in each node?
  - Rank information
    - Very useful but hard to maintain under Insert/Delete
  - Size information
    - Useful and easy to maintain under Insert/Delete
How to augment data structures

1. choose an underlying data structure
2. determine additional information to be maintained in the underlying data structure,
3. develop new operations,
4. verify that the additional information can be maintained for the modifying operations on the underlying data structure.
RB-Tree Augmentation

- Augment x with $\text{Size}(x)$, where
  - $\text{Size}(x) = $ size of subtree rooted at x
  - $\text{Size}(\text{NIL}) = 0$
OS-Select

OS-SELECT(x,i) //page 304

// Select the node with rank i
// in the subtree rooted at x
1. \( r \leftarrow \text{size}[\text{left}[x]] + 1 \)
2. if \( i = r \) then
3. \hspace{1em} return x
4. elseif \( i < r \) then
5. \hspace{1em} return OS-SELECT (left[x], i)
6. else return OS-SELECT (right[x], i-r)
OS-Rank

OS-RANK(x,y)
// Different from text (recursive version)
// Find the rank of y in the subtree rooted at x
1  r = size[left[y]] + 1
2  if x = y then return r
3  else if ( key[x] < key[y] ) then
4    return OS-RANK(x,left[y])
5  else return r + OS-RANK(x,right[y] )

Time Complexity O(log n)
Augmenting RB-Trees

Theorem 14.1, page 309
Let \( f \) be a field that augments a red-black tree \( T \) with \( n \) nodes, and \( f(x) \) can be computed using only the information in nodes \( x, \text{left}[x], \) and \( \text{right}[x], \) including \( f[\text{left}[x]] \) and \( f[\text{right}[x]]. \) Then, we can maintain \( f(x) \) during insertion and deletion without asymptotically affecting the \( O(\log n) \) performance of these operations.

For example,
\[
\text{size}[x] = \text{size}[\text{left}[x]] + \text{size}[\text{right}[x]] + 1 \\
\text{rank}[x] = ?
\]
Examples of augmenting information for RB-Trees

- Parent
- Height
- Any associative function on all previous values or all succeeding values.
- Next
- Previous
Interval Trees

- **Need**: *Dynamic* data structure to store time intervals
- **Application**: Maintain schedule for set of seminars
- **Operations**: Insert, Delete
- Every interval \( j \) has: \( \text{low}[j], \text{high}[j] \)
- **Data Structure**:
  - Augment RB-Tree so that it can store intervals.
  - Ordering based on what key? \( \text{low} \) values? \( \text{high} \) values? \( \frac{\text{high}+\text{low}}{2} \) values? \( \text{(high-low)} \) values?
  - Note that insert and delete are still efficient.
- **New Operation**: Search (find any overlapping interval)
  - Problem with Search!
Augmented Information

- low, high, max
- $\text{max}[x]$ = rightmost high value of all intervals in subtree rooted at $x$
- The value $\text{max}[x]$ of each node can be written as:
  $\text{max}[x] = \text{Max} \{ \text{high}[\text{int}[x]], \text{max}[\text{left}[x]], \text{max}[\text{right}[x]] \}$
- Therefore it can be maintained efficiently under insertions and deletions
INTERVAL-SEARCH (T, j)
// finds an interval in tree T that overlaps interval j,
// else return NIL.
1. \(x = \text{root}[T]\)
2. \(\text{while } x \neq \text{NIL and } j \text{ does not overlap } \text{int}[x] \text{ do}\)
3. \(\text{if left}[x] \neq \text{NIL and } \max[\text{left}[x]] \geq \text{low}[j] \text{ then}\)
4. \(x = \text{left}[x]\)
5. \(\text{else } x = \text{right}[x]\)
6. \(\text{return } x\)

Time Complexity \(O(\log n)\)