

# COT 6936: Topics in Algorithms

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# Presentation Outline

COT 6936:  
Topics in  
Algorithms

Giri  
Narasimhan

LEDA: Library  
of Efficient  
Data  
Structures and  
Algorithms

Features of  
LEDA

Another LEDA  
Example

**1** LEDA: Library of Efficient Data Structures and Algorithms

2 Features of LEDA

3 Another LEDA Example

# LEDA Small Example

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---

## Algorithm 1 Planarity Testing

---

```
1: #include <LEDA/graph/graph_alg.h>
```

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## Algorithm 2 Planarity Testing

---

- 1: `#include <LEDA/graph/graph_alg.h>`
- 2: `using namespace leda;`

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## Algorithm 3 Planarity Testing

---

- 1: `#include <LEDA/graph/graph_alg.h>`
- 2: `using namespace leda;`
- 3: `int main(int argc, char *argv[])`

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## Algorithm 4 Planarity Testing

---

```
1: #include <LEDA/graph/graph_alg.h>
2: using namespace leda;
3: int main(int argc, char *argv[])
4: {
5:     graph G;
```

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## Algorithm 5 Planarity Testing

---

```
1: #include <LEDA/graph/graph_alg.h>
2: using namespace leda;
3: int main(int argc, char *argv[])
4: {
5:     graph G;
6:     string filename(argv[1]);
```

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## Algorithm 6 Planarity Testing

---

```
1: #include <LEDA/graph/graph_alg.h>
2: using namespace leda;
3: int main(int argc, char *argv[])
4: {
5:     graph G;
6:     string filename(argv[1]);
7:     G.read(filename);
```



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## Algorithm 7 Planarity Testing

---

```
1: #include <LEDA/graph/graph_alg.h>
2: using namespace leda;
3: int main(int argc, char *argv[])
4: {
5:     graph G;
6:     string filename(argv[1]);
7:     G.read(filename);
8:     cout << PLANAR(G) << endl;
```

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## Algorithm 8 Planarity Testing

---

```
1: #include <LEDA/graph/graph_alg.h>
2: using namespace leda;
3: int main(int argc, char *argv[])
4: {
5:     graph G;
6:     string filename(argv[1]);
7:     G.read(filename);
8:     cout << PLANAR(G) << endl;
9: }
```

---

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- A C++ library of data structures and algorithms
- Efficient code
- Amply tested
- Extensively documented
- Widely installed

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Example

- **Basic Data Types** float, bigfloat, rational, real, list, map, queue, stack, array, vector, set, matrix, polynomials, string, ...

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- **Basic Data Types** float, bigfloat, rational, real, list, map, queue, stack, array, vector, set, matrix, polynomials, string, ...
- **More Data Types** trees, balanced trees, priority queues, heaps, binomial heaps, Fibonacci heaps, dictionary, hash table, string, tuple, ...

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- **Basic Algorithms** Sorting, Searching, Hashing, alignment, partition, ...

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- **More Data Types** trees, balanced trees, priority queues, heaps, binomial heaps, Fibonacci heaps, dictionary, hash table, string, tuple, ...
- **Basic Algorithms** Sorting, Searching, Hashing, alignment, partition, ...
- **Graph Algorithms** BFS, DFS, MST, Dijkstra, Floyd-Warshall, maxflow, mincut, matching, isomorphism, markov chain, planar graphs, planarity testing, graph drawing algorithms, triangulations, ...



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Example

- **Geometric Data Structures and Algorithms** point, line, ray, segment, polygon, circle, plane, rectangles, triangle, hull, plane sweep, delaunay triangulations, Voronoi diagrams, range trees, interval trees, kd-trees, point locations, segment trees, transformations, ...

# LEDA Overview Cont'd

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- **Linear Algebra** modular arithmetic, long integers, number theory algorithms, ...

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- **Graph Types and Operations** undirected, directed, weighted, planar, adding/removing edges/vertices, faces, ...

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  - `GRAPH<vtype, etype>`:
- **Graphics** windows, colors, scenes, panels, menu, pixmaps, bitmaps, ...

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  - `GRAPH<vtype, etype>`:
- **Graphics** windows, colors, scenes, panels, menu, pixmaps, bitmaps, ...
  - `graph-windows`:

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- **Control Structures**
  - `forall_nodes( $v, G$ )`

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- **Control Structures**
  - `forall_nodes( $v, G$ )`
  - `forall_edges( $e, G$ )`

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## ■ Control Structures

- `forall_nodes( $v, G$ )`
- `forall_edges( $e, G$ )`
- `forall_adj_nodes( $v, w$ )`
- `forall_adj_edges( $e, w$ )`



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## ■ Control Structures

- `forall_nodes(v, G)`
- `forall_edges(e, G)`
- `forall_adj_nodes(v, w)`
- `forall_adj_edges(e, w)`
- `forall_out_edges(e, w)`
- `forall_in_edges(e, w)`

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## ■ Control Structures

- `forall_nodes(v, G)`
- `forall_edges(e, G)`
- `forall_adj_nodes(v, w)`
- `forall_adj_edges(e, w)`
- `forall_out_edges(e, w)`
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## Algorithm 9 Planarity Testing

---

```
#include <LEDA/graph/graph_alg.h>
using namespace leda;
int main(int argc, char *argv[])
{
    graph G;
    string filename(argv[1]); G.read(filename);
    list<edge> edge_list;
```

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---

## Algorithm 10 Planarity Testing

---

```
#include <LEDA/graph/graph_alg.h>
using namespace leda;
int main(int argc, char *argv[])
{
    graph G;
    string filename(argv[1]); G.read(filename);
    list<edge> edge_list;
    if (PLANAR(G, edge_list) == 0)
```

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## Algorithm 11 Planarity Testing

---

```
#include <LEDA/graph/graph_alg.h>
using namespace leda;
int main(int argc, char *argv[])
{
    graph G;
    string filename(argv[1]); G.read(filename);
    list<edge> edge_list;
    if (PLANAR(G, edge_list) == 0)
        forall (x,edge_list) G.print_edge(x);
```

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---

## Algorithm 12 Planarity Testing

---

```
#include <LEDA/graph/graph_alg.h>
using namespace leda;
int main(int argc, char *argv[])
{
    graph G;
    string filename(argv[1]); G.read(filename);
    list<edge> edge_list;
    if (PLANAR(G, edge_list) == 0)
        forall (x,edge_list) G.print_edge(x);
}
```

---

# Sample LEDA Figures

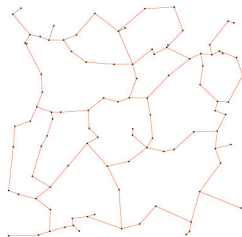
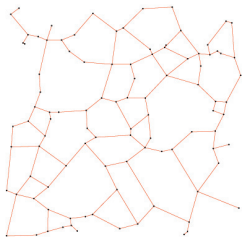
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# Running LEDA

- You can run it on any of the unix-based machines in SCIS (e.g., jaguar, ermine, stoat, . . . )

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- You can run it on any of the unix-based machines in SCIS (e.g., jaguar, ermine, stoat, ...)
- Modify `.cshrc` (or other shell startup config file):

```
alias add2path 'if ("$path:q" ! *"$*" ) set path=( $path $ )'  
setenv LEDAROOT /depot/LEDA-6  
add2path $LEDAROOT/Manual/cmd  
setenv LEDA $LEDAROOT/incl/LEDA
```

# Running LEDA

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and add `$LEDAROOT` to the env variable `LD_LIBRARY_PATH`

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- Next, either login again or type `source .cshrc` to force the shell to read the changes to the config file.

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- Compile the `.c` file using the include flags `$LEDAROOT/incl`. For e.g.,

```
g++ -O3 -I$LEDAROOT/incl -c test.c
```

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- Link and load and create executable using appropriate flags to load libraries

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```
g++ -O3 -I$LEDAROOT/incl -c test.c
```

- Link and load and create executable using appropriate flags to load libraries as shown below

```
g++ -I$LEDAROOT/incl -o test test.o -L$(LEDAROOT) -lleda -lm -lX11
```



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- Link and load and create executable using appropriate flags to load libraries as shown below

```
g++ -I$LEDAROOT/incl -o test test.o -L$(LEDAROOT) -lleda -lm -lX11
```

- Finally you are ready to execute the executable `test`

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```

and add `$LEDAROOT` to the env variable `LD_LIBRARY_PATH`

- Next, either login again or type `source .cshrc` to force the shell to read the changes to the config file.
- Compile the `.c` file using the include flags `$LEDAROOT/incl`. For e.g.,

```
g++ -O3 -I$LEDAROOT/incl -c test.c
```

- Link and load and create executable using appropriate flags to load libraries as shown below

```
g++ -I$LEDAROOT/incl -o test test.o -L$(LEDAROOT) -lleda -lm -lX11
```

- Finally you are ready to execute the executable `test`
- Sample `Makefile` available on your class moodle site.